

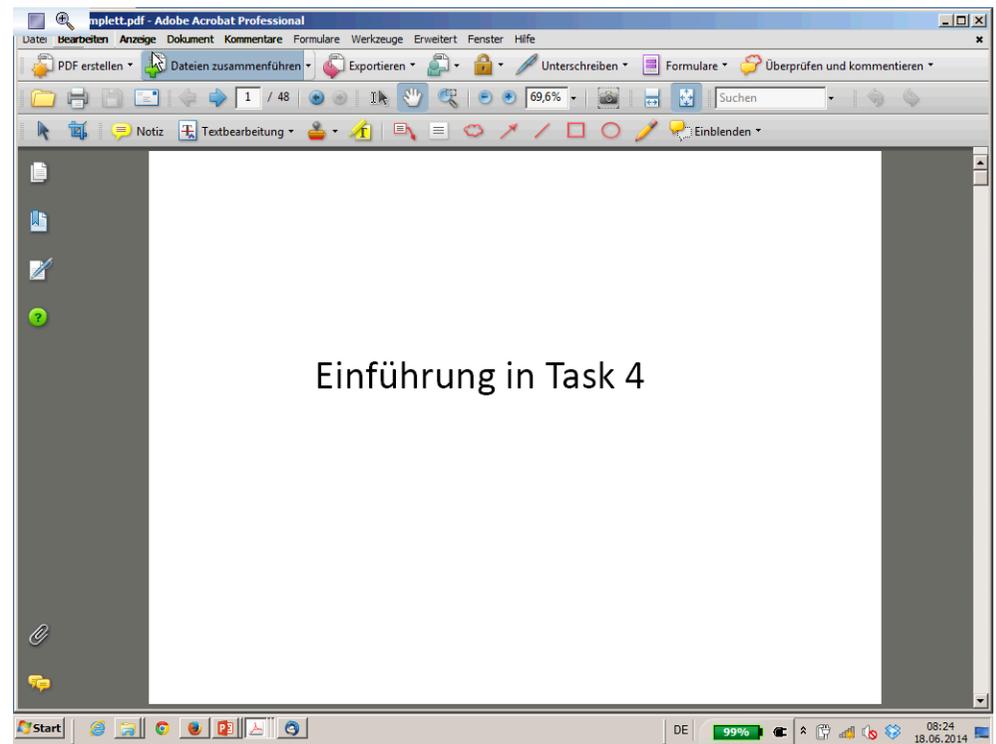
Script generated by TTT

Title: groh: profile1 (18.06.2014)

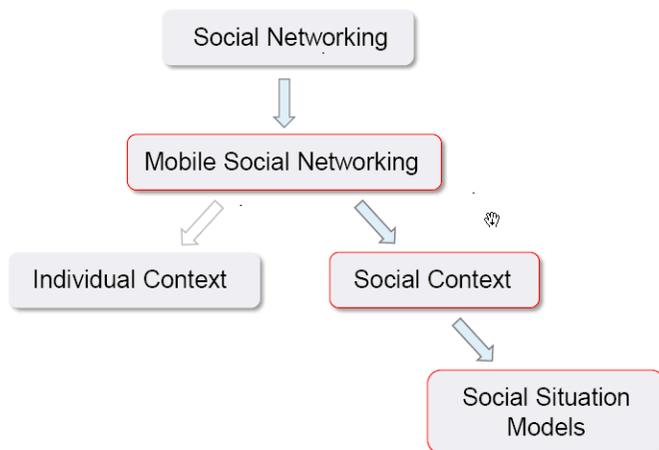
Date: Wed Jun 18 08:24:00 CEST 2014

Duration: 81:26 min

Pages: 32



Social Situation Models as Models of Social Context



Social Situation Models as Models of Social Context

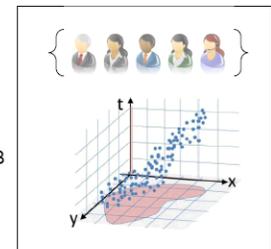
Social Situation:

Co-located social interaction
with full mutual awareness

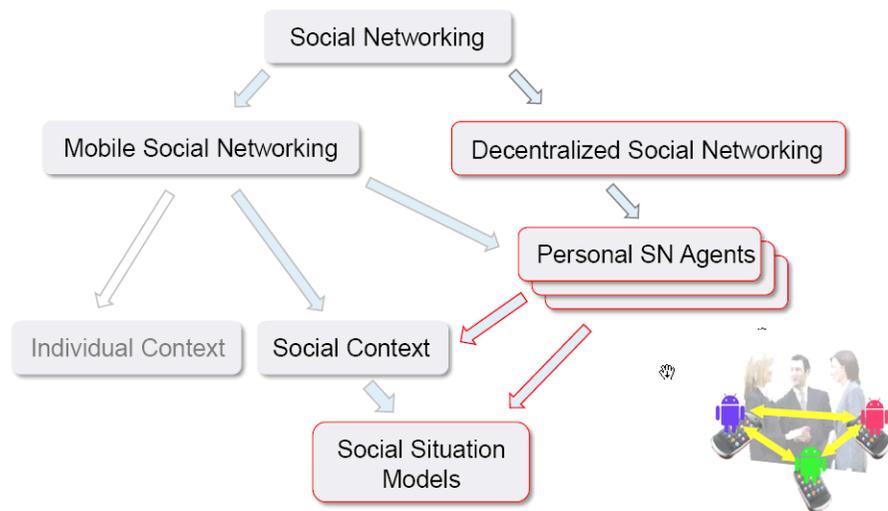


Simplified Social Situation Model:

- Participating persons: P : set of IDs
- Spatio-temporal reference: X : sub-set of $\mathbb{R} \times \mathbb{R}^3$
- $\rightarrow S = (P, X)$

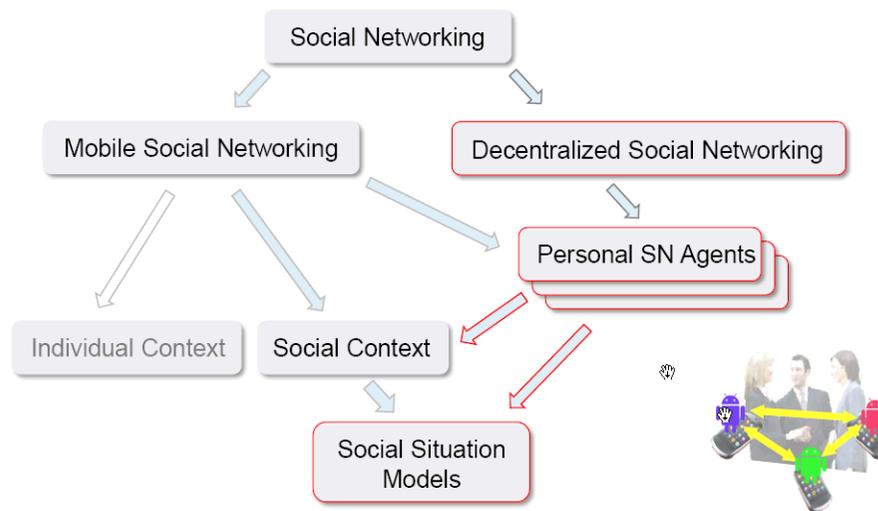


Social Situation Models and Agents



4 / 25

Social Situation Models and Agents



4 / 25

Research Questions

- Method for **measuring** human **social interaction geometry** (mobile → live ; experiment → sociology model)
- **General, quantitative**, algorithmically processable **model** for human social interaction geometry
- Use of model to **detect Social Situations** (e.g. from mobile device measurements)
- Use as social context for **applications** maintaining **privacy**

7 / 18

Research Questions

- Method for **measuring** human **social interaction geometry** (mobile → live ; experiment → sociology model)
- **General, quantitative**, algorithmically processable **model** for human social interaction geometry
- Use of model to **detect Social Situations** (e.g. from mobile device measurements)
- Use as social context for **applications** maintaining **privacy**

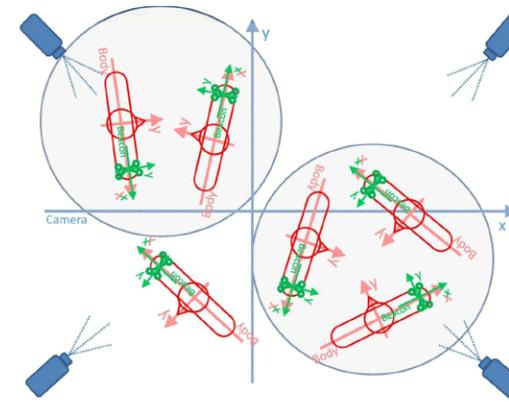
7 / 18

Research Questions

- Method for measuring human social interaction geometry (mobile → live ; experiment → sociology model)
- General, quantitative, algorithmically processable model for human social interaction geometry
- Use of model to detect Social Situations (e.g. from mobile device measurements)
- Use as social context for applications maintaining privacy

7 / 18

Experiment



8 / 18

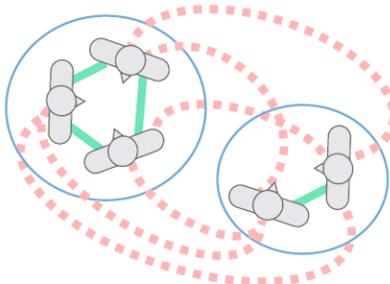
Results

Experiment data: Manual annotation

$|S^{\oplus}| = 321307 (\delta\theta, \delta d)$ pairs corresponding to „in a social situation“
 $|S^{\ominus}| = 398335 (\delta\theta, \delta d)$ pairs corresponding to „not in a social situation“

Example:

$|S^{\oplus}| = 4$
 $|S^{\ominus}| = 6$



10 / 18

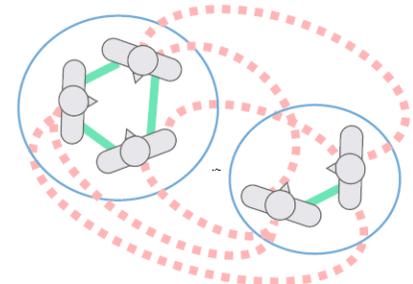
Results

Experiment data: Manual annotation

$|S^{\oplus}| = 321307 (\delta\theta, \delta d)$ pairs corresponding to „in a social situation“
 $|S^{\ominus}| = 398335 (\delta\theta, \delta d)$ pairs corresponding to „not in a social situation“

Example:

$|S^{\oplus}| = 4$
 $|S^{\ominus}| = 6$



10 / 18

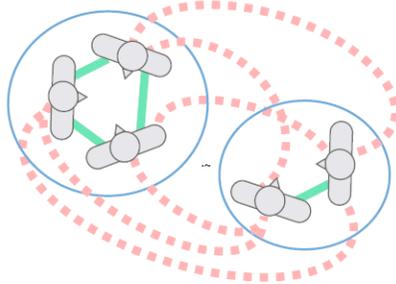
Results

Experiment data: [Manual annotation](#)

$|S^{\oplus}| = 321307 (\delta\theta, \delta d)$ pairs corresponding to „in a social situation“
 $|S^{\ominus}| = 398335 (\delta\theta, \delta d)$ pairs corresponding to „not in a social situation“

Example:

$|S^{\oplus}| = 4$
 $|S^{\ominus}| = 6$



10 / 18

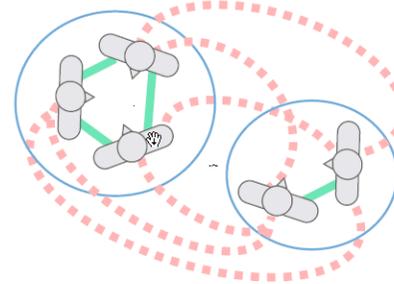
Results

Experiment data: [Manual annotation](#)

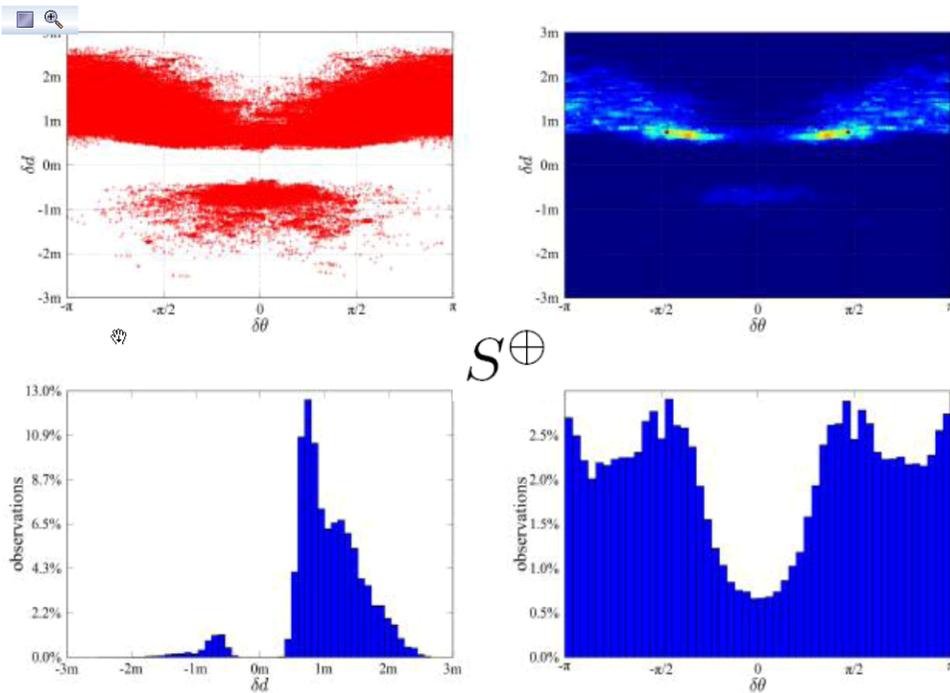
$|S^{\oplus}| = 321307 (\delta\theta, \delta d)$ pairs corresponding to „in a social situation“
 $|S^{\ominus}| = 398335 (\delta\theta, \delta d)$ pairs corresponding to „not in a social situation“

Example:

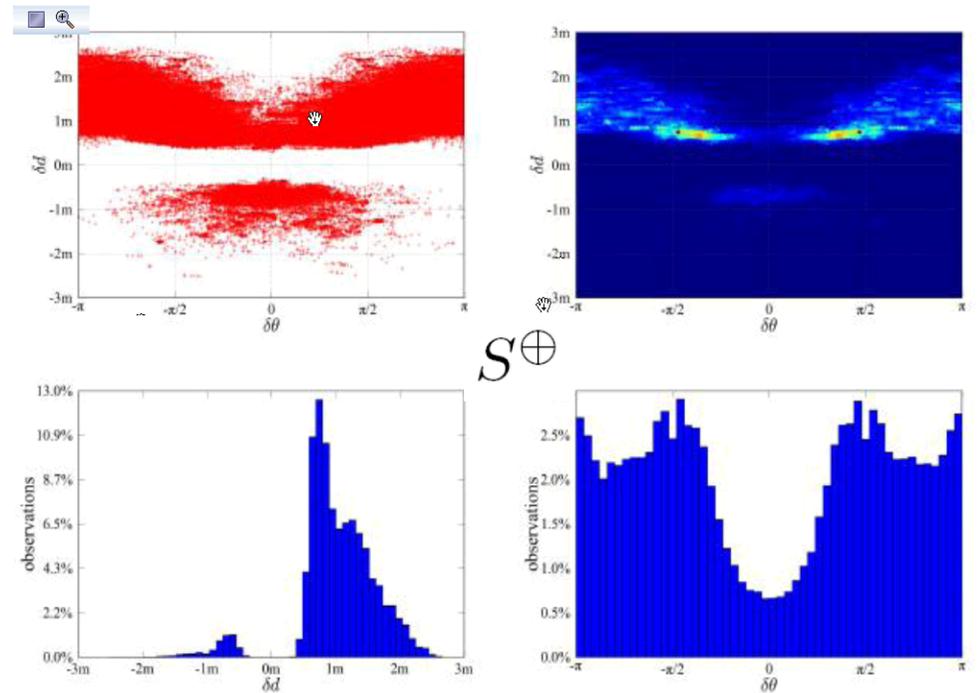
$|S^{\oplus}| = 4$
 $|S^{\ominus}| = 6$



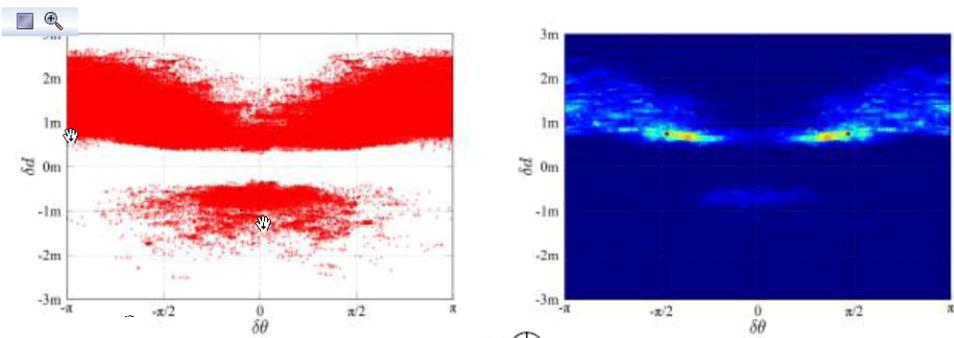
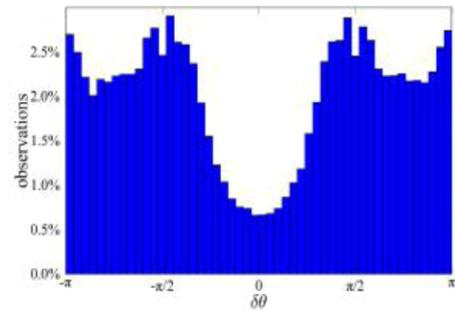
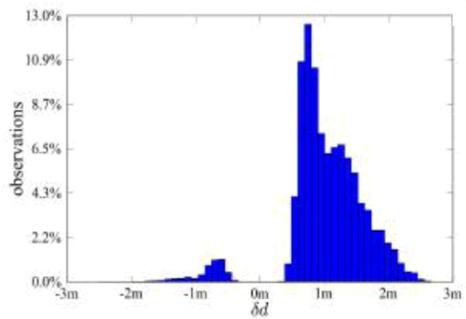
10 / 18



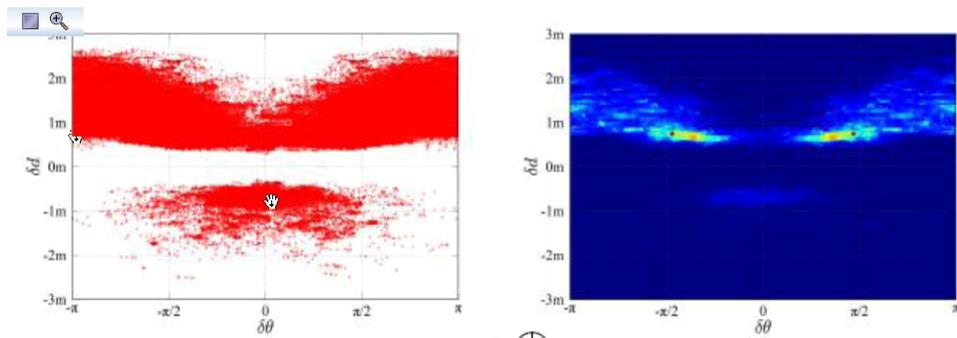
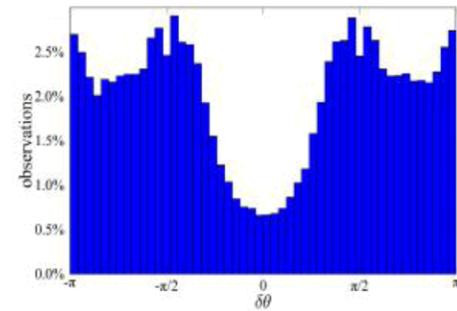
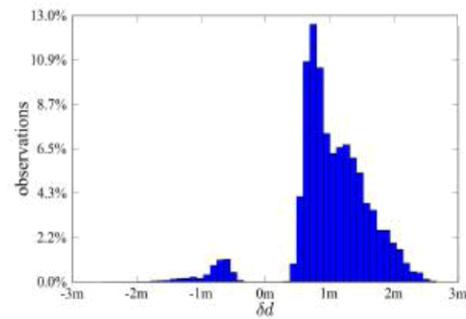
11 / 18



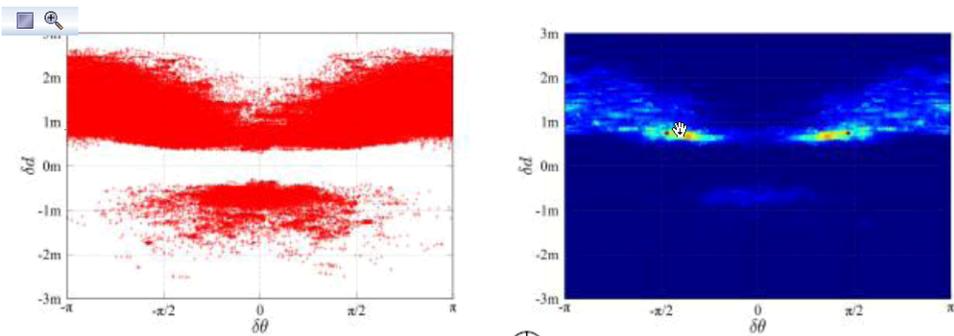
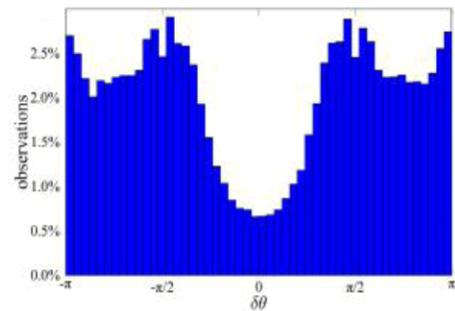
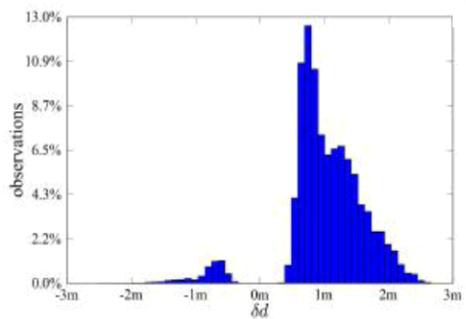
11 / 18


 S^{\oplus}


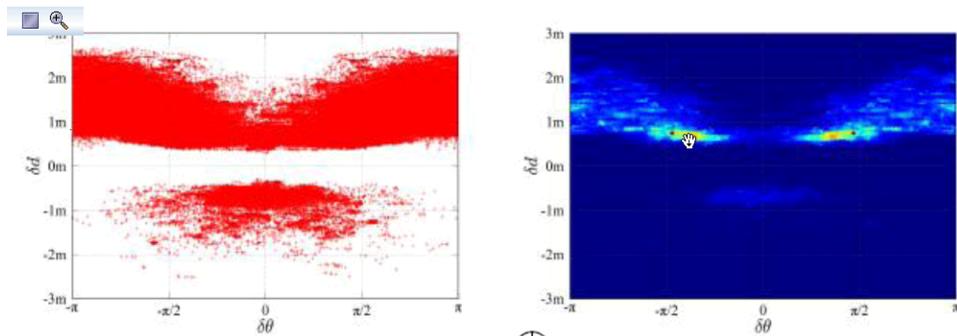
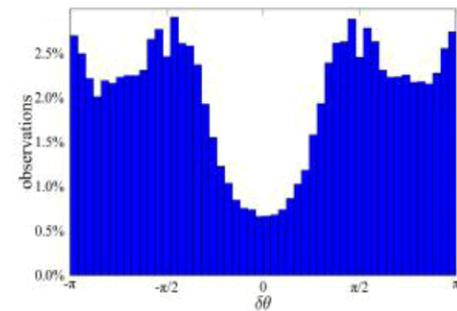
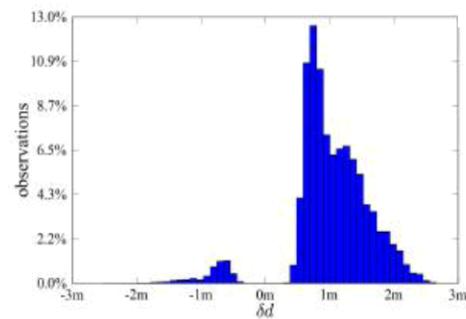
11 / 18


 S^{\oplus}


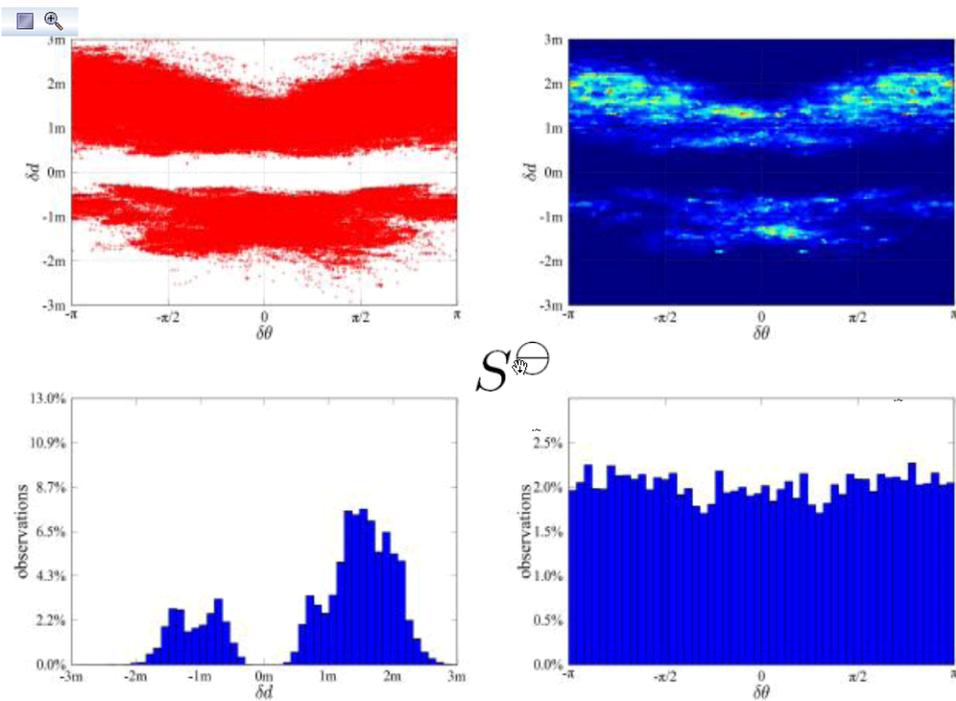
11 / 18


 S^{\oplus}


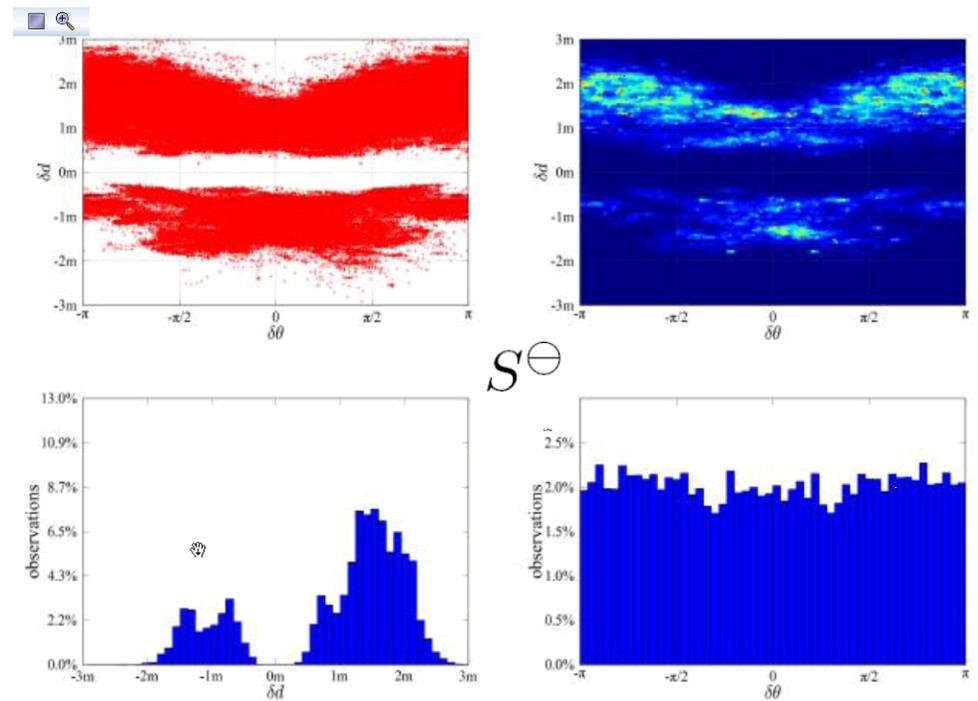
11 / 18


 S^{\oplus}


11 / 18



12 / 18

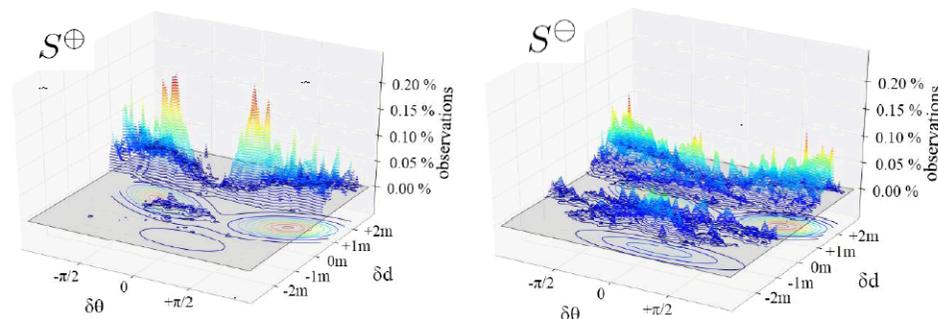


12 / 18

Results

$S^{\oplus} = \{ (\delta\theta, \delta d) \}$ pairs in a social situation
 $S^{\ominus} = \{ (\delta\theta, \delta d) \}$ pairs not in a social situation

→ train (EM-algorithm) one **Gaussian Mixture Model** for S^{\oplus} and one for S^{\ominus}
 → $p^{\oplus}(\delta\theta, \delta d)$ and $p^{\ominus}(\delta\theta, \delta d)$



13 / 18

Classification Results

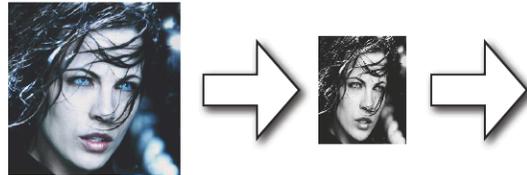
Classifier	Accuracy*
Gaussian Mixture Model (3 Gaussians)	74,34 %
Gaussian Mixture Model (5 Gaussians)	74,67 %
Gaussian Mixture Model (7 Gaussians)	74,59 %
Naive Bayes	65,45 %
Support Vector Machine (Polyn. Kernel)	77,81 %

(*) w. 10-fold cross validation

14 / 18

Preprocessing

- Two-dimensional images correspond to one-dimensional vectors



			0.47
0.99	0.97	...	0.24
...

0.12	0.8	...	0.47	0.99	0.97	...
------	-----	-----	------	------	------	-----

Derivation

- Eigenvalue decomposition of the covariance matrix

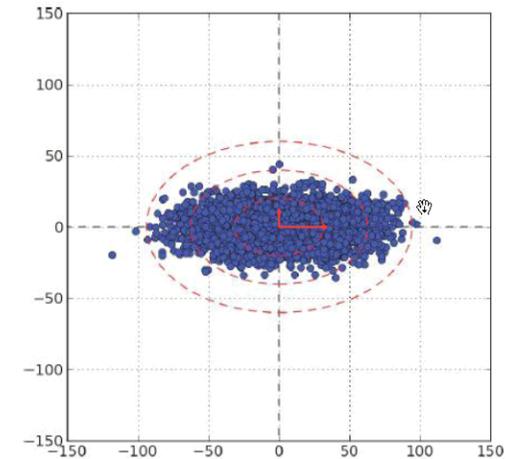
$$C = E \Lambda E^T = \begin{pmatrix} e_{11} & \dots & e_{1n} \\ \vdots & \ddots & \vdots \\ e_{m1} & \dots & e_{mn} \end{pmatrix} \begin{pmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{pmatrix} \begin{pmatrix} e_{11} & \dots & e_{m1} \\ \vdots & \ddots & \vdots \\ e_{1n} & \dots & e_{mn} \end{pmatrix}$$

where the columns of E denote the eigenvectors of C and each λ the respective eigenvalue

- In case of PCA, the principal components are the ones associated with the highest eigenvalues, hence

$$|\lambda_1| > |\lambda_2| > \dots > |\lambda_n|$$

Example



Derivation

- Eigenvalue decomposition of the covariance matrix

$$C = E \Lambda E^T = \begin{pmatrix} e_{11} & \dots & e_{1n} \\ \vdots & \ddots & \vdots \\ e_{m1} & \dots & e_{mn} \end{pmatrix} \begin{pmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{pmatrix} \begin{pmatrix} e_{11} & \dots & e_{m1} \\ \vdots & \ddots & \vdots \\ e_{1n} & \dots & e_{mn} \end{pmatrix}$$

where the columns of E denote the eigenvectors of C and each λ the respective eigenvalue

- In case of PCA, the principal components are the ones associated with the highest eigenvalues, hence

$$|\lambda_1| > |\lambda_2| > \dots > |\lambda_n|$$

Preprocessing

- Concatenation of the N_p images for each person p yields the final training dataset

$$X = \begin{pmatrix} i_{11} & i_{21} & \dots & i_{N_1} \\ i_{12} & i_{22} & \dots & i_{N_2} \\ \vdots & \vdots & \ddots & \vdots \\ i_{1d} & i_{2d} & \dots & i_{N_d} \end{pmatrix}$$

where i_{jk} denotes the k -th component of the j -th image (now represented as d -dimensional vectors) and $N = \sum_{p \in P} N_p$

- A second data structure is mandatory to store the assignment of column indexes to persons

Eigenfaces

- Reconsider the general form of the eigenvalue equation

$$\Sigma' x = \lambda x$$

- Substitute $X^T X$ for Σ'

$$X^T X x = \lambda x$$

- Multiply the above equation with X

$$X X^T X x = \lambda X x$$

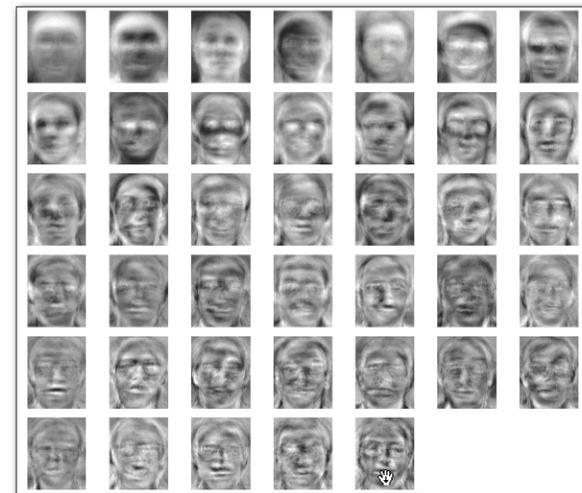
- Substitute Σ for $X X^T$

$$\Sigma X x = \lambda X x$$

Eigenfaces

- Next, PCA is used to determine the set of eigenfaces (typically ~ 40) that are best fit to reconstruct the training data
- Beware:
A 92×112 image yields a 10304-dimensional vector.
- How can we deal with the eigenvalue decomposition of a 10304×10304 covariance matrix?
- Actually only ~ 40 eigenpairs need to be computed!

Eigenfaces





Task 2: Face Recognition

main To Dos:

- built a database of face-images and detect faces with the help of Open-CV (given C++ class)
- understand and implement Principal Component Analysis
- implement a KNN classifier
- apply and test your implementation to the test-database.

