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⑫ More Search Trees

⑬ Union, Intersection, Difference on BSTs

⑭ Tries and Patricia Tries

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## 2-3 Trees

```
datatype 'a tree23 = ()  
| Node2 ('a tree23) 'a ('a tree23)  
| Node3 ('a tree23) 'a ('a tree23) 'a ('a tree23)
```

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```
isin <l, a, m, b, r> x =  
(case cmp x a of  
 | LT => isin l x  
 | EQ => True  
 | GT => case cmp x b of  
 | LT => isin m x  
 | EQ => True  
 | GT => isin r x)
```

*isin*

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## Structural invariant $bal$

All leaves are at the same level:

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All leaves are at the same level:

$$bal \langle \rangle = True$$

$$bal \langle l, \_, r \rangle = (bal\ l \wedge bal\ r \wedge h(l) = h(r))$$

$$\begin{aligned} bal \langle l, \_, m, \_, r \rangle = \\ (bal\ l \wedge bal\ m \wedge bal\ r \wedge h(l) = h(m) \wedge h(m) = h(r)) \end{aligned}$$

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## Insertion

The idea:

$$Leaf \rightsquigarrow Node2$$

$$Node2 \rightsquigarrow Node3$$

$Node3 \rightsquigarrow \text{overflow}$ , pass 1 element back up

## Insertion

Two possible return values:

- tree accommodates new element without increasing height:  $T_i t$

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- tree overflows:  $Up_i l x r$

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```
datatype 'a upi = Ti ('a tree23)
  | Upi ('a tree23) 'a ('a tree23)
```

## Insertion

Two possible return values:

- tree accommodates new element without increasing height:  $T_i t$
- tree overflows:  $Up_i l x r$

```
datatype 'a upi = Ti ('a tree23)
  | Upi ('a tree23) 'a ('a tree23)
```

$tree_i :: 'a upi \Rightarrow 'a tree23$



## Insertion

Two possible return values:

- tree accommodates new element without increasing height:  $T_i t$
- tree overflows:  $Up_i l x r$

**datatype**  $'a up_i = T_i ('a tree23)$   
 $| Up_i ('a tree23) 'a ('a tree23)$

$tree_i :: 'a up_i \Rightarrow 'a tree23$

$tree_i (T_i t) = t$

$tree_i (Up_i l a r) = \langle l, a, r \rangle$

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## Insertion

$insert :: 'a \Rightarrow 'a tree23 \Rightarrow 'a tree23$   
 $insert x t = tree_i (ins x t)$

88



## Insertion

Two possible return values:

- tree accommodates new element without increasing height:  $T_i t$
- tree overflows:  $Up_i l x r$

**datatype**  $'a up_i = T_i ('a tree23)$   
 $| Up_i ('a tree23) 'a ('a tree23)$

$tree_i :: 'a up_i \Rightarrow 'a tree23$

$tree_i (T_i t) = t$

$tree_i (Up_i l a r) = \langle l, a, r \rangle$

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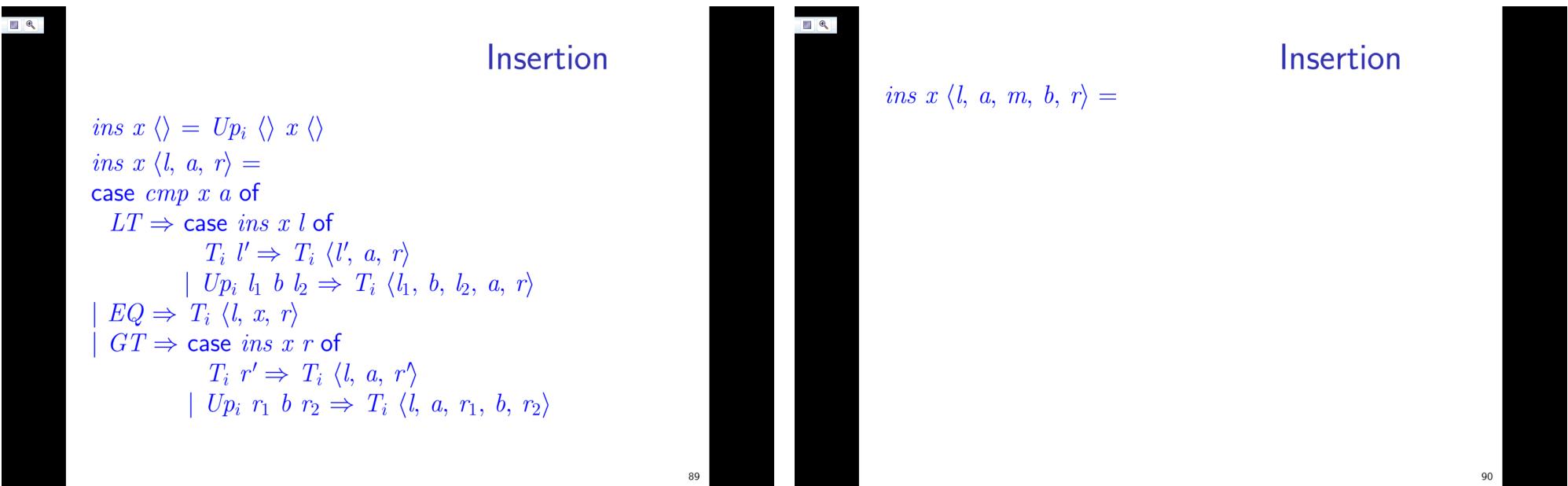
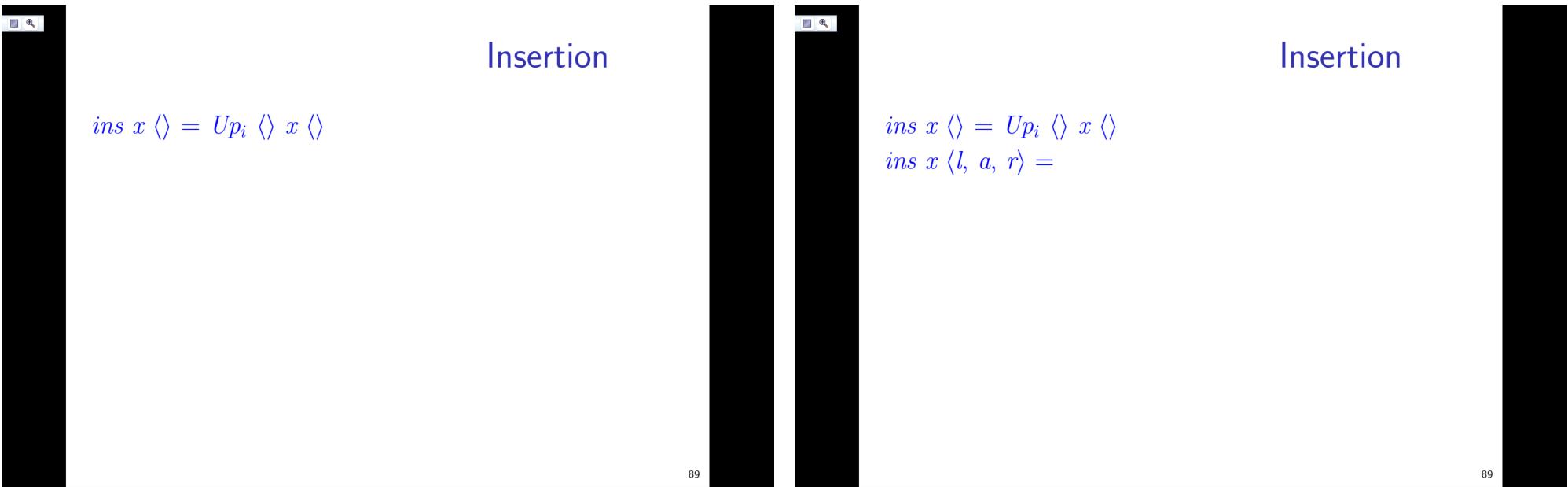


## Insertion

$insert :: 'a \Rightarrow 'a tree23 \Rightarrow 'a tree23$   
 $insert x t = tree_i (ins x t)$

$ins :: 'a \Rightarrow 'a tree23 \Rightarrow 'a up_i$

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## Insertion

```
ins x ⟨l, a, m, b, r⟩ =  
case cmp x a of  
| LT ⇒ case ins x l of  
    Ti l' ⇒ Ti ⟨l', a, m, b, r⟩  
    | Upi l1 c l2 ⇒ Upi ⟨l1, c, l2⟩ a ⟨m, b, r⟩  
| EQ ⇒ Ti ⟨l, a, m, b, r⟩  
| GT ⇒  
    case cmp x b of  
    | LT ⇒  
        case ins x m of  
        Ti m' ⇒ Ti ⟨l, a, m', b, r⟩  
        | Upi m1 c m2 ⇒ Upi ⟨l, a, m1⟩ c ⟨m2, b, r⟩  
    | EQ ⇒ Ti ⟨l, a, m, b, r⟩  
    | GT ⇒
```

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## Insertion preserves *bal*

Lemma  
 $\text{bal } t \implies \text{bal } (\text{tree}_i (\text{ins } a t))$

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## Insertion

```
ins x ⟨l, a, m, b, r⟩ =
```

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## Insertion preserves *bal*

Lemma  
 $\text{bal } t \implies \text{bal } (\text{tree}_i (\text{ins } a t))$

91

**Proof** by induction on  $t$ .



## Insertion

```
ins x ⟨⟩ = Upi ⟨⟩ x ⟨⟩  
ins x ⟨l, a, r⟩ =  
case cmp x a of  
| LT ⇒ case ins x l of  
    Ti l' ⇒ Ti ⟨l', a, r⟩  
    | Upi l1 b l2 ⇒ Ti ⟨l1, b, l2, a, r⟩  
| EQ ⇒ Ti ⟨l, x, r⟩  
| GT ⇒ case ins x r of  
    Ti r' ⇒ Ti ⟨l, a, r'⟩  
    | Upi r1 b r2 ⇒ Ti ⟨l, a, r1, b, r2⟩
```

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Lemma  
 $\text{bal } t \implies \text{bal } (\text{tree}_i (\text{ins } a t))$

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## Insertion

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ins x ⟨⟩ = Upi ⟨⟩ x ⟨⟩  
ins x ⟨l, a, r⟩ =  
case cmp x a of  
| LT ⇒ case ins x l of  
    Ti l' ⇒ Ti ⟨l', a, r⟩  
    | Upi l1 b l2 ⇒ Ti ⟨l1, b, l2, a, r⟩  
| EQ ⇒ Ti ⟨l, x, r⟩  
| GT ⇒ case ins x r of  
    Ti r' ⇒ Ti ⟨l, a, r'⟩  
    | Upi r1 b r2 ⇒ Ti ⟨l, a, r1, b, r2⟩
```

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## Insertion preserves *bal*

Lemma  
 $\text{bal } t \implies \text{bal } (\text{tree}_i (\text{ins } a t))$

91



## Insertion preserves $bal$

Lemma

$$bal t \implies bal (\text{tree}_i (\text{ins } a \ t))$$

**Proof** by induction on  $t$ .

91



## Insertion preserves $bal$

Lemma

$$bal t \implies bal (\text{tree}_i (\text{ins } a \ t)) \wedge h(\text{ins } a \ t) = h(t)$$

where  $h :: 'a \ up_i \Rightarrow \text{nat}$

$$h(T_i \ t) = h(t)$$

$$h(Up_i \ l \ a \ r) = h(l)$$

**Proof** by induction on  $t$ .

91



## Insertion preserves $bal$

Lemma

$$bal t \implies bal (\text{tree}_i (\text{ins } a \ t))$$

where  $h :: 'a \ up_i \Rightarrow \text{nat}$

$$h(T_i \ t) = h(t)$$

$$h(Up_i \ l \ a \ r) = h(l)$$

**Proof** by induction on  $t$ .

91



## Insertion preserves $bal$

Lemma

$$bal t \implies bal (\text{tree}_i (\text{ins } a \ t)) \wedge h(\text{ins } a \ t) = h(t)$$

where  $h :: 'a \ up_i \Rightarrow \text{nat}$

$$h(T_i \ t) = h(t)$$

$$h(Up_i \ l \ a \ r) = h(l)$$

**Proof** by induction on  $t$ . Base and step automatic.

Corollary

$$bal t \implies bal (\text{insert } a \ t)$$

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## Deletion

The idea:

Two possible return values:

- height unchanged:  $T_d t$
- height decreased by 1:  $Up_d t$

**datatype** '*a* upd =  $T_d ('a\ tree23)$  |  $Up_d ('a\ tree23)$

$$\begin{aligned}tree_d (T_d t) &= t \\tree_d (Up_d t) &= t\end{aligned}$$

## Deletion

$delete :: 'a \Rightarrow 'a\ tree23 \Rightarrow 'a\ tree23$

$delete :: 'a \Rightarrow 'a\ tree23 \Rightarrow 'a\ tree23$   
 $delete\ x\ t = tree_d (del\ x\ t)$

## Deletion

## Deletion

```
delete :: 'a ⇒ 'a tree23 ⇒ 'a tree23  
delete x t = treed (del x t)  
  
del :: 'a ⇒ 'a tree23 ⇒ 'a upd
```

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```
del x ⟨l, a, r⟩ =  
(case cmp x a of  
| LT ⇒ node21 (del x l) a r  
| EQ ⇒ let (a', t) = split_min r in node22 l a' t  
| GT ⇒ node22 l a (del x r))
```

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```
del x ⟨l, a, r⟩ =  
(case cmp x a of  
| LT ⇒ node21 (del x l) a r  
| EQ ⇒ let (a', t) = split_min r in node22 l a' t  
| GT ⇒ node22 l a (del x r))
```

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```
del x ⟨l, a, r⟩ =  
(case cmp x a of  
| LT ⇒ node21 (del x l) a r  
| EQ ⇒ let (a', t) = split_min r in node22 l a' t  
| GT ⇒ node22 l a (del x r))
```

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```
node21 (Td t1) a t2 = Td ⟨t1, a, t2⟩  
node21 (Upd t1) a ⟨t2, b, t3⟩ = Upd ⟨t1, a, t2, b, t3⟩  
node21 (Upd t1) a ⟨t2, b, t3, c, t4⟩ =  
Td ⟨⟨t1, a, t2⟩, b, ⟨t3, c, t4⟩⟩
```

## Deletion preserves $bal$

After 13 simple lemmas:

**Lemma**

$$bal\ t \implies bal\ (\text{tree}_d\ (\text{del}\ x\ t))$$

**Corollary**

$$bal\ t \implies bal\ (\text{delete}\ x\ t)$$

## Beyond 2-3 trees

## Beyond 2-3 trees

```
datatype 'a tree234 =
  Leaf | Node2 ... | Node3 ... | Node4 ...
```

Like 2-3 trees, but with many more cases

The general case:

B-trees and  $(a, b)$ -trees

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## Relationship to 2-3-4 trees

Idea: encode 2-3-4 trees as binary trees;

101



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Idea: encode 2-3-4 trees as binary trees;  
use color to express grouping

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use color to express grouping

$$\langle \rangle \approx \langle \rangle$$

101



## Relationship to 2-3-4 trees

Idea: encode 2-3-4 trees as binary trees;  
use color to express grouping

$$\begin{aligned}\langle \rangle &\approx \langle \rangle \\ \langle t_1, a, t_2 \rangle &\approx \langle t_1, a, t_2 \rangle \\ \langle t_1, a, t_2, b, t_3 \rangle &\approx \langle \langle t_1, a, t_2 \rangle, b, t_3 \rangle \text{ or } \langle t_1, a, \langle t_2, b, t_3 \rangle \rangle\end{aligned}$$

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## Relationship to 2-3-4 trees

Idea: encode 2-3-4 trees as binary trees;  
use color to express grouping

$$\begin{aligned} \langle \rangle &\approx \langle \rangle \\ \langle t_1, a, t_2 \rangle &\approx \langle t_1, a, t_2 \rangle \\ \langle t_1, a, t_2, b, t_3 \rangle &\approx \langle \langle t_1, a, t_2 \rangle, b, t_3 \rangle \text{ or } \langle t_1, a, \langle t_2, b, t_3 \rangle \rangle \\ \langle t_1, a, t_2, b, t_3, c, t_4 \rangle &\approx \langle \langle t_1, a, t_2 \rangle, b, \langle t_3, c, t_4 \rangle \rangle \end{aligned}$$

Red means "I am part of a bigger node"

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## Structural invariants

- The root is

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## Structural invariants

- The root is Black.
- Every  $\langle \rangle$  is considered Black.

102

## Structural invariants

- The root is Black.
- Every  $\langle \rangle$  is considered Black.
- If a node is Red,

102



## Structural invariants

- The root is Black.
- Every  $\langle \rangle$  is considered Black.
- If a node is Red, its children are Black.
- All paths from a node to a leaf have the same number of

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## Red-black trees

**datatype**  $color = Red \mid Black$

**datatype**

$'a rbt = Leaf \mid Node\ color\ ('a\ tree)\ 'a\ ('a\ tree)$

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## Red-black trees

**datatype**  $color = Red \mid Black$

**datatype**

$'a rbt = Leaf \mid Node\ color\ ('a\ tree)\ 'a\ ('a\ tree)$

Abbreviations:

$$\begin{aligned} \langle \rangle &\equiv Leaf \\ \langle l, a, c, r \rangle &\equiv Node\ l\ a\ c\ r \end{aligned}$$

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## Red-black trees

**datatype**  $color = Red \mid Black$

**datatype**

$'a rbt = Leaf \mid Node\ color\ ('a\ tree)\ 'a\ ('a\ tree)$

Abbreviations:

$$\begin{aligned} \langle \rangle &\equiv Leaf \\ \langle l, a, c, r \rangle &\equiv Node\ l\ a\ c\ r \\ R\ l\ a\ r &\equiv Node\ l\ a\ Red\ r \end{aligned}$$

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## Red-black trees

**datatype**  $\text{color} = \text{Red} \mid \text{Black}$

**datatype**

$'a \text{ rbt} = \text{Leaf} \mid \text{Node color ('a tree) } 'a \text{ ('a tree)}$

Abbreviations:

$$\langle \rangle \equiv \text{Leaf}$$

$$\langle l, a, c, r \rangle \equiv \text{Node } l \ a \ c \ r$$

$$R \ l \ a \ r \equiv \text{Node } l \ a \ \text{Red} \ r$$

$$B \ l \ a \ r \equiv \text{Node } l \ a \ \text{Black} \ r$$

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## Structural invariants

$rbt :: 'a rbt \Rightarrow \text{bool}$

$rbt \ t = (\text{invc } t \wedge \text{invh } t \wedge \text{color } t = \text{Black})$

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## Structural invariants

**datatype**  $\text{color} = \text{Red} \mid \text{Black}$

**datatype**

$'a \text{ rbt} = \text{Leaf} \mid \text{Node color ('a tree) } 'a \text{ ('a tree)}$

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## Red-black trees

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## Structural invariants

$invh :: 'a rbt \Rightarrow bool$

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## Structural invariants

$invh :: 'a rbt \Rightarrow bool$

$invh \langle \rangle = True$

$invh \langle l, \_, \_, r \rangle = (invh l \wedge invh r \wedge bh(l) = bh(r))$

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## Structural invariants

$invh :: 'a rbt \Rightarrow bool$

$invh \langle \rangle = True$

$invh \langle l, \_, \_, r \rangle = (invh l \wedge invh r \wedge bh(l) = bh(r))$

$bheight :: 'a rbt \Rightarrow nat$

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## Structural invariants

$invh :: 'a rbt \Rightarrow bool$

$invh \langle \rangle = True$

$invh \langle l, \_, \_, r \rangle = (invh l \wedge invh r \wedge bh(l) = bh(r))$

$bheight :: 'a rbt \Rightarrow nat$

$bh(\langle \rangle) = 0$

$bh(\langle l, \_, c, \_ \rangle) =$

$(\text{if } c = Black \text{ then } bh(l) + 1 \text{ else } bh(l))$

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## Logarithmic height

Lemma

$$rbt\ t \implies h(t) \leq 2 * \log_2 |t|_1$$

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## Structural invariants

$$rbt :: 'a rbt \Rightarrow \text{bool}$$

$$rbt\ t = (\text{invc}\ t \wedge \text{invh}\ t \wedge \text{color}\ t = \text{Black})$$

$$\text{invc} :: 'a rbt \Rightarrow \text{bool}$$

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## Structural invariants

$$\text{invh} :: 'a rbt \Rightarrow \text{bool}$$

$$\text{invh} \langle \rangle = \text{True}$$

$$\text{invh} \langle l, \_, \_, r \rangle = (\text{invh}\ l \wedge \text{invh}\ r \wedge \text{bh}(l) = \text{bh}(r))$$

$$\text{bheight} :: 'a rbt \Rightarrow \text{nat}$$

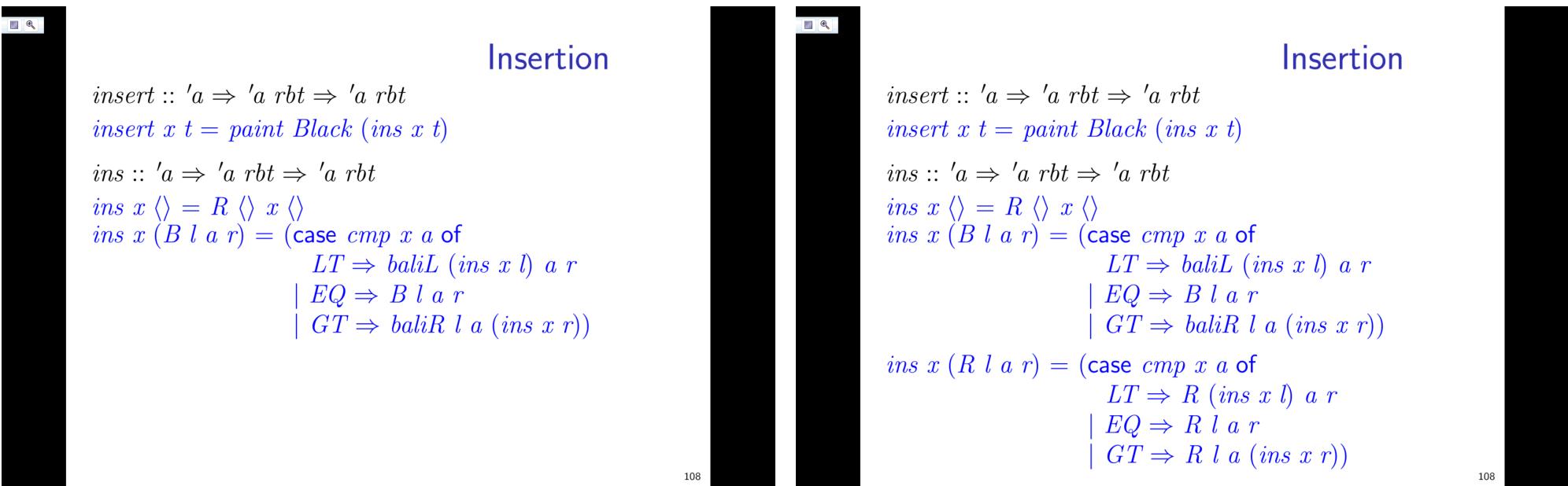
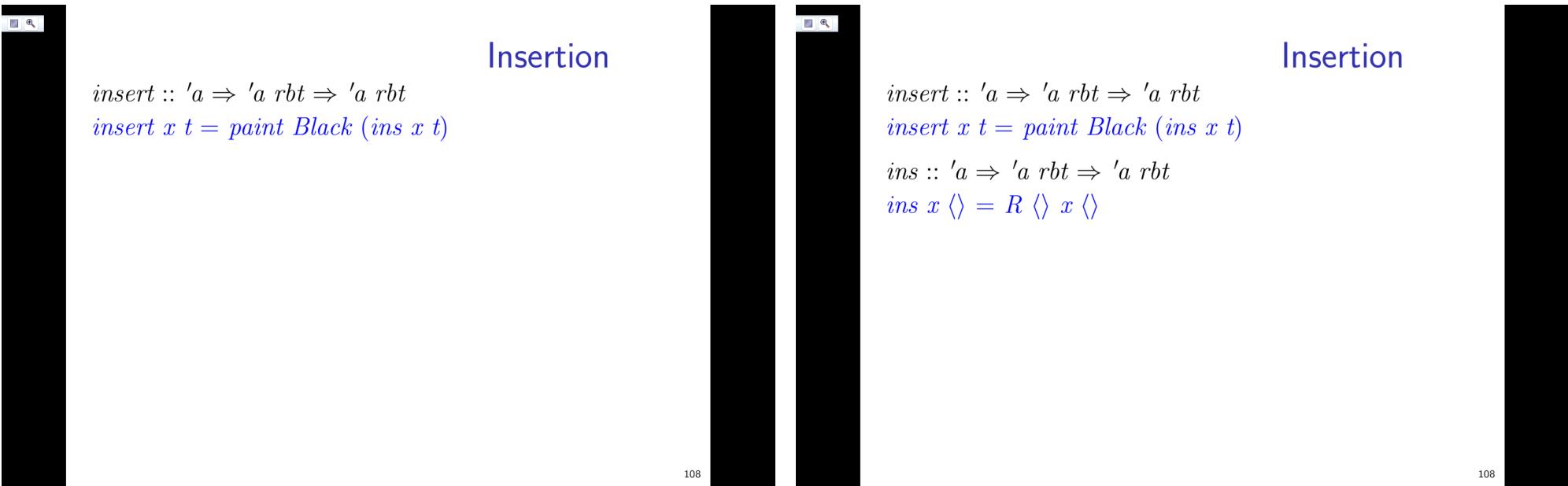
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## Insertion

$$\text{insert} :: 'a \Rightarrow 'a rbt \Rightarrow 'a rbt$$

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## Adjusting colors

$baliL, baliR :: 'a rbt \Rightarrow 'a \Rightarrow 'a rbt \Rightarrow 'a rbt$



## Adjusting colors

$baliL, baliR :: 'a rbt \Rightarrow 'a \Rightarrow 'a rbt \Rightarrow 'a rbt$

- Combine arguments  $l\ a\ r$  into tree, ideally  $\langle l, a, r \rangle$

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## Adjusting colors

$baliL, baliR :: 'a rbt \Rightarrow 'a \Rightarrow 'a rbt \Rightarrow 'a rbt$

- Combine arguments  $l\ a\ r$  into tree, ideally  $\langle l, a, r \rangle$
- Treat invariant violation Red-Red in  $l/r$

$$\begin{aligned} baliL (R (R t_1 a_1 t_2) a_2 t_3) a_3 t_4 \\ = R (B t_1 a_1 t_2) a_2 (B t_3 a_3 t_4) \end{aligned}$$



## Adjusting colors

$baliL, baliR :: 'a rbt \Rightarrow 'a \Rightarrow 'a rbt \Rightarrow 'a rbt$

- Combine arguments  $l\ a\ r$  into tree, ideally  $\langle l, a, r \rangle$
- Treat invariant violation Red-Red in  $l/r$

$$\begin{aligned} baliL (R (R t_1 a_1 t_2) a_2 t_3) a_3 t_4 \\ = R (B t_1 a_1 t_2) a_2 (B t_3 a_3 t_4) \\ baliL (R t_1 a_1 (R t_2 a_2 t_3)) a_3 t_4 \\ = R (B t_1 a_1 t_2) a_2 (B t_3 a_3 t_4) \end{aligned}$$

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## Adjusting colors

*baliL, baliR* ::  $'a\ rbt \Rightarrow 'a \Rightarrow 'a\ rbt \Rightarrow 'a\ rbt$

- Combine arguments  $l \ a \ r$  into tree, ideally  $\langle l, a, r \rangle$
  - Treat invariant violation Red-Red in  $l/r$   

$$\begin{aligned} baliL(R(Rt_1a_1t_2)a_2t_3) & a_3t_4 \\ &= R(Bt_1a_1t_2)a_2(Bt_3a_3t_4) \\ baliL(Rt_1a_1(Rt_2a_2t_3)) & a_3t_4 \\ &= R(Bt_1a_1t_2)a_2(Bt_3a_3t_4) \end{aligned}$$
  - Principle: replace Red-Red by Red-Black

$$\begin{aligned} &= R(B t_1 a_1 t_2) a_2 (B t_3 a_3 t_4) \\ baliL(R t_1 a_1 (R t_2 a_2 t_3)) a_3 t_4 \\ &= R(B t_1 a_1 t_2) a_2 (B t_3 a_3 t_4) \end{aligned}$$

Principle: replace Red-Red by Red-Black

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## Preservation of invariant

After 14 simple lemmas:

## Theorem

*rbt t*  $\implies$  *rbt (insert x t)*

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## Adjusting colors

*baliL, baliR* ::  $'a\ rbt \Rightarrow 'a \Rightarrow 'a\ rbt \Rightarrow 'a\ rbt$

- Combine arguments  $l$   $a$   $r$  into tree, ideally  $\langle l, a, r \rangle$
  - Treat invariant violation Red-Red in  $l/r$ 

$$\begin{aligned} baliL(R(R t_1 a_1 t_2) a_2 t_3) a_3 t_4 \\ = R(B t_1 a_1 t_2) a_2 (B t_3 a_3 t_4) \\ baliL(R t_1 a_1 (R t_2 a_2 t_3)) a_3 t_4 \\ = R(B t_1 a_1 t_2) a_2 (B t_3 a_3 t_4) \end{aligned}$$
  - Principle: replace Red-Red by Red-Black
  - Final equation:  
 $baliL l a r = B l a r$

$$\begin{aligned} baliL & (R (R t_1 a_1 t_2) a_2 t_3) a_3 t_4 \\ &= R (B t_1 a_1 t_2) a_2 (B t_3 a_3 t_4) \\ baliL & (R t_1 a_1 (R t_2 a_2 t_3)) a_3 t_4 \\ &= R (B t_1 a_1 t_2) a_2 (B t_3 a_3 t_4) \end{aligned}$$

- Principle: replace Red-Red by Red-Black

- Final equation:  
 $baliL \cdot l \cdot g \cdot r \equiv B \cdot l \cdot g \cdot r$

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## Proof in CLRS

1.1. **Background**

It is well known that the human brain has two hemispheres, left and right, and that they have different functions. For example, the left hemisphere is mainly responsible for language processing, while the right hemisphere is mainly responsible for spatial reasoning and non-verbal processing. This difference in function is often referred to as lateralization.

**Somatosensory.** When the word "somatosensory" is mentioned, most people think of the sense of touch, which is often referred to as "tactile" or "kinesthesia". However, somatosensory also refers to other types of sensations, such as pain, temperature, and pressure. In this paper, we will focus on the sense of touch, which is often referred to as "tactile" or "kinesthesia".

**Motor.** We usually want to consider the motor in the whole brain, but it is often useful to consider the motor in one hemisphere at a time. For example, if we want to move our right arm, we can do this by activating the motor cortex in the right hemisphere. We can then move our right arm only if the right hemisphere is active. If the left hemisphere is active, the right arm will not move.

We can distinguish three types of movement: 1) voluntary movement, 2) reflexive movement, and 3) involuntary movement. Voluntary movement is controlled by the prefrontal cortex, reflexive movement is controlled by the cerebellum, and involuntary movement is controlled by the basal ganglia.

**Care of the brain.**

Figure 15.5 shows the situation for the first 5 weeks of life. At week 1, the brain is very small and the cerebellum is not yet fully developed. At week 2, the brain begins to grow rapidly, and the cerebellum begins to develop. At week 3, the brain continues to grow rapidly, and the cerebellum continues to develop. At week 4, the brain continues to grow rapidly, and the cerebellum continues to develop. At week 5, the brain continues to grow rapidly, and the cerebellum continues to develop.

Now, let's show that it is important to take care of the brain during the first 5 weeks of life. If we don't take care of the brain during the first 5 weeks of life, the brain will not develop properly, and the cerebellum will not develop properly. This will lead to various problems, such as learning difficulties, memory problems, and physical disabilities.

4. Because this brain cortex is  $p_1 \wedge p_2 \wedge p_3 \wedge p_4 \wedge p_5$  in the 5 weeks of life.

5. The brain cortex is  $p_1 \wedge p_2 \wedge p_3 \wedge p_4 \wedge p_5$  in the 5 weeks of life.

6. We have already argued that  $p_1 \wedge p_2 \wedge p_3 \wedge p_4 \wedge p_5$  is true, because  $p_1 \wedge p_2 \wedge p_3 \wedge p_4 \wedge p_5$  is true.

1.2. **Conclusion**

Figure 15.5: Care of the brain. The diagram shows two states of a brain model. State 1 shows a single black circle representing the brain. State 2 shows two circles, one black and one white, representing the brain and cerebellum respectively.

Take care of your brain! The brain is the most important organ in your body. It controls everything you do, from breathing to thinking. So, it's important to take care of your brain. Here are some tips:

1. Eat healthy food. A healthy diet is good for your brain.
2. Exercise regularly. Exercise helps keep your brain healthy.
3. Get enough sleep. Sleep is important for your brain to function properly.
4. Stay mentally active. Engage in activities that challenge your mind, such as reading, solving puzzles, and playing games.
5. Avoid drugs and alcohol. These substances can damage your brain.

Remember, your brain is your most valuable asset. Take care of it!

Footnote 1: *It is well known that the human brain has two hemispheres, left and right, and that they have different functions. For example, the left hemisphere is mainly responsible for language processing, while the right hemisphere is mainly responsible for spatial reasoning and non-verbal processing. This difference in function is often referred to as lateralization.*

Footnote 2: *When the word "somatosensory" is mentioned, most people think of the sense of touch, which is often referred to as "tactile" or "kinesthesia". However, somatosensory also refers to other types of sensations, such as pain, temperature, and pressure. In this paper, we will focus on the sense of touch, which is often referred to as "tactile" or "kinesthesia".*

Footnote 3: *We usually want to consider the motor in the whole brain, but it is often useful to consider the motor in one hemisphere at a time. For example, if we want to move our right arm, we can do this by activating the motor cortex in the right hemisphere. We can then move our right arm only if the right hemisphere is active. If the left hemisphere is active, the right arm will not move.*

Footnote 4: *We can distinguish three types of movement: 1) voluntary movement, 2) reflexive movement, and 3) involuntary movement. Voluntary movement is controlled by the prefrontal cortex, reflexive movement is controlled by the cerebellum, and involuntary movement is controlled by the basal ganglia.*

Footnote 5: *Figure 15.5 shows the situation for the first 5 weeks of life. At week 1, the brain is very small and the cerebellum is not yet fully developed. At week 2, the brain begins to grow rapidly, and the cerebellum begins to develop. At week 3, the brain continues to grow rapidly, and the cerebellum continues to develop. At week 4, the brain continues to grow rapidly, and the cerebellum continues to develop. At week 5, the brain continues to grow rapidly, and the cerebellum continues to develop.*

Footnote 6: *Now, let's show that it is important to take care of the brain during the first 5 weeks of life. If we don't take care of the brain during the first 5 weeks of life, the brain will not develop properly, and the cerebellum will not develop properly. This will lead to various problems, such as learning difficulties, memory problems, and physical disabilities.*

Footnote 7: *4. Because this brain cortex is  $p_1 \wedge p_2 \wedge p_3 \wedge p_4 \wedge p_5$  in the 5 weeks of life.*

Footnote 8: *5. The brain cortex is  $p_1 \wedge p_2 \wedge p_3 \wedge p_4 \wedge p_5$  in the 5 weeks of life.*

Footnote 9: *6. We have already argued that  $p_1 \wedge p_2 \wedge p_3 \wedge p_4 \wedge p_5$  is true, because  $p_1 \wedge p_2 \wedge p_3 \wedge p_4 \wedge p_5$  is true.*

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## Deletion

Tricky functions: *baldL*, *baldR*, *combine*

12 short but tricky to find invariant lemmas with short proofs. The worst:

$$\begin{aligned} & \llbracket \text{invh } t; \text{invc } t \rrbracket \\ \implies & \text{invh } (\text{del } x \ t) \wedge \\ & (\text{color } t = \text{Red} \wedge \\ & \quad \text{bh}(\text{del } x \ t) = \text{bh}(t) \wedge \text{invc } (\text{del } x \ t) \vee \\ & \quad \text{color } t = \text{Black} \wedge \\ & \quad \text{bh}(\text{del } x \ t) = \text{bh}(t) - 1 \wedge \text{invc2 } (\text{del } x \ t)) \end{aligned}$$

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## Deletion

Tricky functions: *baldL*, *baldR*, *combin*

12 short but tricky to find invariant lemmas with short proofs. The worst:

$$\begin{aligned} & \llbracket \text{invh } t; \text{ invc } t \rrbracket \\ \implies & \text{invh } (\text{del } x \ t) \wedge \\ & (\text{color } t = \text{Red} \wedge \\ & \quad \text{bh}(\text{del } x \ t) = \text{bh}(t) \wedge \text{invc } (\text{del } x \ t) \vee \\ & \quad \text{color } t = \text{Black} \wedge \\ & \quad \text{bh}(\text{del } x \ t) = \text{bh}(t) - 1 \wedge \text{invc2 } (\text{del } x \ t)) \end{aligned}$$

## Theorem

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## Code and proof in CLRS

11.

## Source of code

### Insertion:

Okasaki's Purely Functional Data Structures

### **Deletion:**

Stefan Kahrs. *Red Black Trees with Types*  
J. Functional Programming. 1996.

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