

Script generated by TTT

Title: Petter: Compilerbau (13.07.2015)

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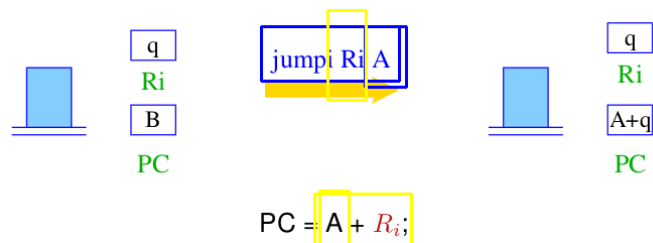
Duration: 65:05 min

Pages: 35

## The switch-Statement

### Idea:

- Suppose choosing from multiple options in *constant time* if possible
- use a *jump table* that, at the  $i$ th position, holds a jump to the  $i$ th alternative
- in order to realize this idea, we need an *indirect jump* instruction



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- in order to realize this idea, we need an *indirect jump* instruction

## Consecutive Alternatives

Let `switch s` be given with  $k$  consecutive `case` alternatives:

```
switch (e) {  
  case 0:  $s_0$ ; break;  
  :  
  case  $k-1$ :  $s_{k-1}$ ; break;  
  default:  $s_k$ ; break;  
}
```

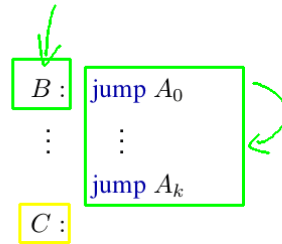
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  :
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  default: sk; break;
}
```

Define  $\text{code}^i s \rho$  as follows:

```
codei s ρ = codeiR e ρ
             checki 0 k B
A0: codei s0 ρ
      jump C
:
:
Ak: codei sk ρ
      jump C
```



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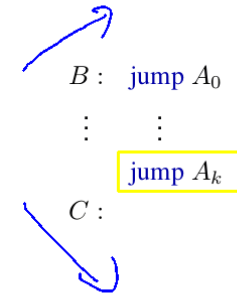
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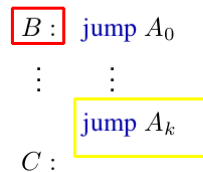
$\text{check}^i l u B$  checks if  $l \leq R_i < u$  holds and jumps accordingly.

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## Translation of the $\text{check}^i$ Macro

The macro  $\text{check}^i l u B$  checks if  $l \leq R_i < u$ . Let  $k = u - l$ .

- if  $l \leq R_i < u$  it jumps to  $B + R_i - l$
- if  $R_i < l$  or  $R_i \geq u$  it jumps to  $B + u = B + k$



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we define:

```
check0 l u B = loadc Ri+1 l
                geq Ri+2 Ri Ri+1}
                jumpz Ri+2 E
                sub Ri Ri Ri+1}
                loadc Ri+1 u
                geq Ri+2 Ri Ri+1}
                jumpz Ri+2 D
E: loadc Ri B
D: jumpi Ri B
B: jump A0
:
:
jump Ak
C:
```

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- if  $R_i < l$  or  $R_i \geq u$  it jumps to  $C$

we define:

```
 $check^i l u B$  = loadc  $R_{i+1}$  0  
                 geq  $R_{i+2} R_i R_{i+1}$    B : jump  $A_0$   
                 jumpz  $R_{i+2} E$   
                 sub  $R_i R_i R_{i+1}$        :   :  
                 loadc  $R_{i+1} u$          :   :  
                 geq  $R_{i+2} R_i R_{i+1}$    C : jump  $A_k$   
                 jumpz  $R_{i+2} D$   
E : loadc  $R_i (u - l)$   
D : jumpi  $R_i B$ 
```

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## Improvements for Jump Tables

This translation is only suitable for *certain* switch-statement.

- In case the table starts with 0 instead of  $u$  we don't need to subtract it from  $e$  before we use it as index
- if the value of  $e$  is **guaranteed** to be in the interval  $[l, u]$ , we can *not* omit *check* *completely*

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## General translation of switch-Statements

In general, the values of the various cases may be far apart:

- generate an **if**-ladder, that is, a sequence of **if**-statements
- for  $n$  cases, an **if**-cascade (tree of conditionals) can be generated  $\leadsto O(\log n)$  tests
- if the sequence of numbers has small gaps ( $\leq 3$ ), a jump table may be smaller and faster
- one could generate several jump tables, one for each sets of consecutive cases
- an **if** cascade can be re-arranged by using information from *profiling*, so that paths executed more frequently require fewer tests

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## Code Synthesis

### Chapter 4: Functions

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## Ingredients of a Function

The definition of a function consists of

- a **name** with which it can be called;
- a specification of its **formal parameters**;
- possibly a **result type**;
- a sequence of **statements**.

In C we have:

$code_R^i f \rho = loadc R_i \_f$  with  $\_f$  starting address of  $f$

Observe:

- function names must have an address assigned to them
- since the size of functions is unknown before they are translated, the addresses of forward-declared functions must be inserted later

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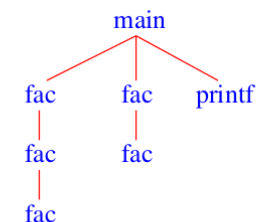
## Memory Management in Functions

```
int fac(int x) {
    if (x <= 0) return 1;
    else return x * fac(x-1);
}

int main(void) {
    int n;
    n = fac(2) + fac(1);
    printf("%d", n);
}
```

At run-time several **instances** may be active, that is, the function has been called but has not yet returned.

The recursion tree in the example:



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## Memory Management in Function Variables

The **formal parameters** and the **local variables** of the various **instances** of a function must be kept separate

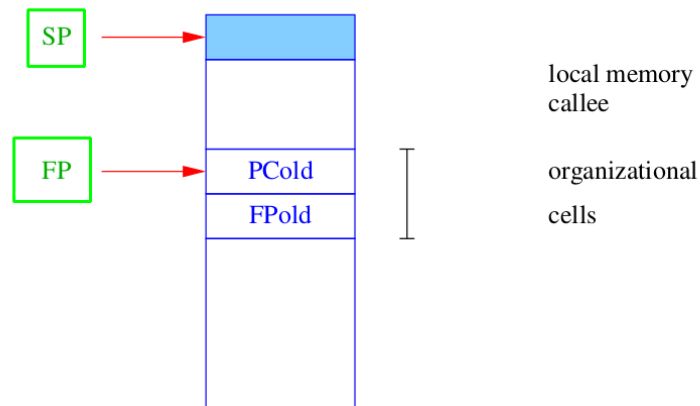
**Idea for implementing functions:**

- set up a region of memory each time it is called
- in sequential programs this memory region can be allocated on the stack
- thus, each instance of a function has its own region on the stack
- these regions are called **stack frames**

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## Organization of a Stack Frame

- **stack** representation: grows upwards
- **SP** points to the last used stack cell



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## Split of Obligations

*void f(int a, int b);*  
*void f(a, b) int a, int b;*

### Definition

Let  $f$  be the current function that calls a function  $g$ .

- $f$  is dubbed **caller**
- $g$  is dubbed **callee**

The code for managing function calls has to be split between caller and callee.

This split cannot be done arbitrarily since some information is only known in that caller or only in the callee.

### Observation:

The space requirement for parameters is only known by the caller:

Example: `printf`

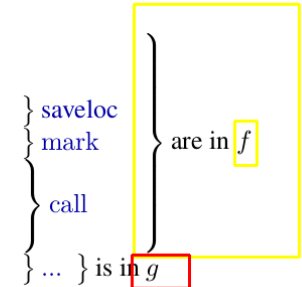
*f(42, " ");*

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## Principle of Function Call and Return

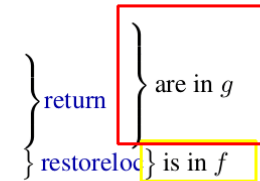
actions taken on entering  $g$ :

1. compute the start address of  $g$
2. compute actual parameters in globals
3. backup of caller-save registers
4. backup of FP
5. set the new FP
6. back up of PC and jump to the beginning of  $g$
7. copy actual params to locals



actions taken on leaving  $g$ :

1. compute the result into  $R_0$
2. restore FP, SP
3. return to the call site in  $f$ , that is, restore PC
4. restore the caller-save registers



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## Managing Registers during Function Calls

The two register sets (global and local) are used as follows:

- automatic variables live in **local** registers  $R_i$
- intermediate results also live in **local** registers  $R_i$
- parameters live in **global** registers  $R_i$  (with  $i \leq 0$ )
- global variables:

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convention:

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convention:

- the  $i$ th argument of a function is passed in register  $R_i$   $R_{-i}$

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convention:

- the  $i$ th argument of a function is passed in register  $R_i$
- the result of a function is stored in  $R_0$
- local registers are saved before calling a function

### Definition

Let  $f$  be a function that calls  $g$ . A register  $R_i$  is called

- *caller-saved* if  $f$  backs up  $R_i$  and  $g$  may overwrite it
- *callee-saved* if  $f$  does not back up  $R_i$ , and  $g$  must restore it before returning

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## Translation of Function Calls

A function call  $g(e_1, \dots, e_n)$  is translated as follows:

```

codeRi g(e1, ... en) ρ = codeRi g ρ
                        codeRi+1 e1 ρ
                        ⋮
                        codeRi+n en ρ
                        move R-1 Ri+1 ✓
                        ⋮
                        move R-n Ri+n ✓
                        saveloc R1 Ri-1
                        mark
                        call Ri
                        restoreloc R1 Ri-1
                        move Ri R0
    
```

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                        ⋮
                        move R-n Ri+n
                        saveloc R1 Ri-1
                        mark
                        call Ri
                        restoreloc R1 Ri-1
                        move Ri R0
    
```

New instructions:

- `saveloc Ri Rj` pushes the registers  $R_i, R_{i+1} \dots R_j$  onto the stack
- `mark` backs up the organizational cells
- `call Ri` calls the function at the address in  $R_i$
- `restoreloc Ri Rj` pops  $R_j, R_{j-1}, \dots, R_i$  off the stack

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## Rescuing EP and FP

The instruction `mark` allocates stack space for the return value and the organizational cells and backs up `FP` and `PC`.

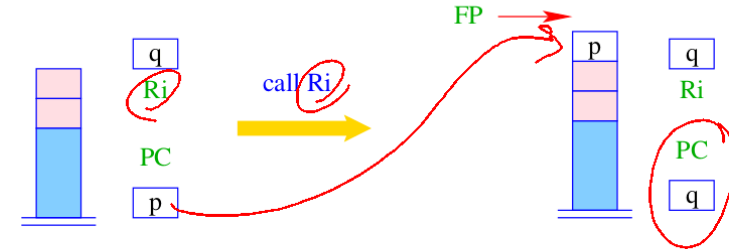


~~S[SP+1] = FP;~~  
~~S[SP+2] = PC;~~  
 S[SP+1] = FP;  
 S[SP+2] = PC;  
 SP = SP + 2;

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## Calling a Function

The instruction `call` rescues the value of `PC+1` onto the stack and sets `FP` and `PC`.



SP = SP + 1;  
 S[SP] = PC;  
 FP = SP;  
 PC = Ri;

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## Result of a Function

The global register set is also used to communicate the result value of a function:

`codei return e ρ` = `codeRi e ρ`  
`move R0 Ri`  
`return`

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alternative without result value:

`codei return ρ` = `return`

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## Result of a Function

The global register set is also used to communicate the result value of a function:

$$\text{code}^i \text{ return } e \ \rho = \text{code}^i_{R} e \ \rho$$

```

move R0 Ri
return
    
```

alternative without result value:

$$\text{code}^i \text{ return } \rho = \text{return}$$

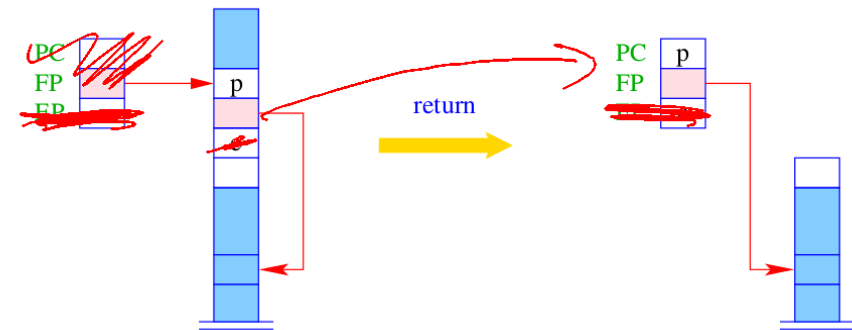
*global* registers are otherwise not used inside a function body:

- advantage: at any point in the body another function can be called without backing up *global* registers
- ~~disadvantage~~: on entering a function, all *global* registers must be saved

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## Return from a Function

The instruction `return` relinquishes control of the current stack frame, that is, it restores `PC`, `EP` and `FP`.



$$\begin{aligned} \text{PC} &= \text{S}[\text{FP}]; & \text{EP} &= \text{S}[\text{FP}-2]; \\ \text{SP} &= \text{FP}-3; & \text{FP} &= \text{S}[\text{SP}+2]; \end{aligned}$$

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## Translation of Functions

The translation of a function is thus defined as follows:

$$\text{code}^l t_r \mathbf{f}(\text{args}) \{ \text{decls } ss \} \rho = \text{enter } q$$

```

move Rl+1 R-1
:
move Rl+n R-n
codel+n+1 ss ρ'
return
    
```

Assumptions:

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Assumptions:

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## Translation of Functions

The translation of a function is thus defined as follows:

```
codel t_r f(args){decls ss} ρ = enter q
                                move Rl+1 R-1
                                ⋮
                                move Rl+n R-n
                                codel+n+1 ss ρ'
                                return
```

Assumptions:

- the function has  $n$  parameters
- the local variables are stored in registers  $R_1, \dots, R_l$
- the parameters of the function are in  $R_{-1}, \dots, R_{-n}$
- $\rho'$  is obtained by extending  $\rho$  with the bindings in *decls* and the function parameters *args*

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## Translation of Whole Programs

A program  $P = F_1; \dots; F_n$  must have a single main function.

```
code1 P ρ = loadc R1 _main
             mark
             call R1
             halt
_f1 : code1 F1 ρ ⊕ ρf1
      ⋮
_fn : code1 Fn ρ ⊕ ρfn
```

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## Translation of the fac-function

Consider:

<code>int fac(int x) {</code>	<code>_A: move R<sub>2</sub> R<sub>1</sub></code>	<code>x*fac(x-1)</code>
<code>if (x&lt;=0) then</code>	<code>i = 3 move R<sub>3</sub> R<sub>1</sub></code>	<code>x-1</code>
<code>return 1;</code>	<code>i = 4 loadc R<sub>4</sub> 1</code>	
<code>else</code>	<code>sub R<sub>3</sub> R<sub>3</sub> R<sub>4</sub></code>	
<code>return x*fac(x-1);</code>	<code>i = 3 move R<sub>-1</sub> R<sub>3</sub></code>	<code>fac(x-1)</code>
<code>}</code>	<code>loadc R<sub>3</sub> _fac</code>	
<code>_fac: <del>enter 5</del></code>	<code>saveloc R<sub>1</sub> R<sub>2</sub></code>	
<code>move R<sub>1</sub> R<sub>-1</sub></code>	<code>mark</code>	
<code>i = 2 move R<sub>2</sub> R<sub>1</sub></code>	<code>call R<sub>3</sub></code>	
<code>loadc R<sub>3</sub> 0</code>	<code>restoreloc R<sub>1</sub> R<sub>2</sub></code>	
<code>leq R<sub>2</sub> R<sub>2</sub> R<sub>3</sub></code>	<code>move R<sub>3</sub> R<sub>0</sub></code>	
<code>jumpz R<sub>2</sub> _A</code>	<code>mul R<sub>2</sub> R<sub>2</sub> R<sub>3</sub></code>	
<code>loadc R<sub>2</sub> 1</code>	<code>move R<sub>0</sub> R<sub>2</sub></code>	<code>return x*...</code>
<code>move R<sub>0</sub> R<sub>2</sub></code>	<code>return</code>	
<code>return</code>	<code>_B: return</code>	
<code>jump _B</code>	<code>code is dead</code>	

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End of presentation. Click to exit.