

Script generated by TTT

Title: Seidl: Virtual_Machines (07.06.2016)

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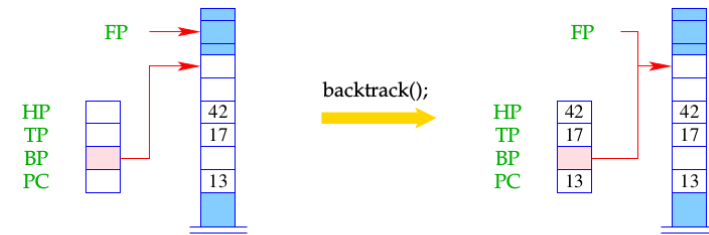
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33.2 Trailing and Resetting Variables

Idea

- The variables which have been created since the last backtrack point can be removed together with their bindings by popping the heap !!
- Bindings of variables in the **old** heap section, though, must be reset **explicitly**.
- These are therefore recorded in the trail.

Calling the run-time function `void backtrack()` yields:



```
void backtrack() {  
    FP = BP; HP = HPold;  
    reset (TPold, TP);  
    TP = TPold; PC = negCont;  
}
```

where the run-time function `reset()` undoes the bindings of variables established **since** the backtrack point.

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Functions `void trail(ref u)` and `void reset (ref y, ref x)` can thus be implemented as:

```
void trail (ref u) {  
    if (u < S[BP-2]) {  
        TP = TP+1;  
        T[TP] = u;  
    }  
}  
  
void reset (ref x, ref y) {  
    for (ref u=y; x<u; u--)  
        H[T[u]] = (R,T[u]);  
}
```

Here, `S[BP-2]` represents the heap pointer when creating the last backtrack point.

33.3 Wrapping it Up

Assume that the predicate q/k is defined by the clauses $rr \equiv r_1, \dots, r_f$ ($f > 1$). We provide code for:

- **setting** up the backtrack point;
- successively **trying** the alternatives;
- **deleting** the backtrack point.

This means:

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Example

```
s(X) ← t( $\bar{X}$ )
s(X) ←  $\bar{X} = a$ 
```

The translation of the predicate s yields:

```
s/1:  setbtp  A:  pushenv 1  B:  pushenv 1
      try A    mark C    putref 1
      delbtp   putref 1  uatom a
      jump B   call t/1  popenv
      C:  popenv
```

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```
codeP rr = q/k: setbtp
               try A1
               ...
               try Af-1
               delbtp
               jump Af
A1: codeC r1
...
Af: codeC rf
```

Remark

- We delete the backtrack point **before** the last alternative.
- We **jump** to the last alternative — never to return to the present frame!

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303

Example

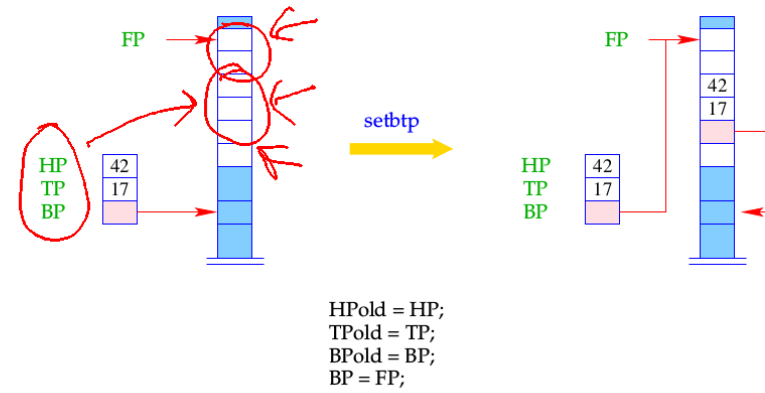
$$s(X) \leftarrow t(\bar{X})$$

$$s(X) \leftarrow \bar{X} = a$$

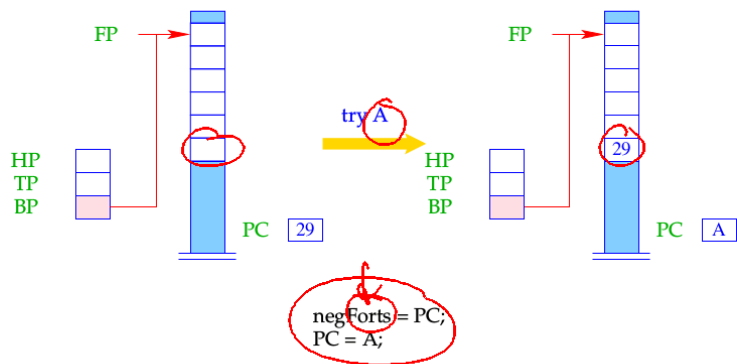
The translation of the predicate `s` yields:

<code>s/1:</code>	<code>setbtp</code>	<code>A:</code>	<code>pushenv 1</code>	<code>B:</code>	<code>pushenv 1</code>
	<code>try A</code>		<code>mark C</code>		<code>putref 1</code>
	<code>delbtp</code>		<code>putref 1</code>		<code>uatom a</code>
	<code>jump B</code>		<code>call t/1</code>		<code>popenv</code>
		<code>C:</code>	<code>popenv</code>		

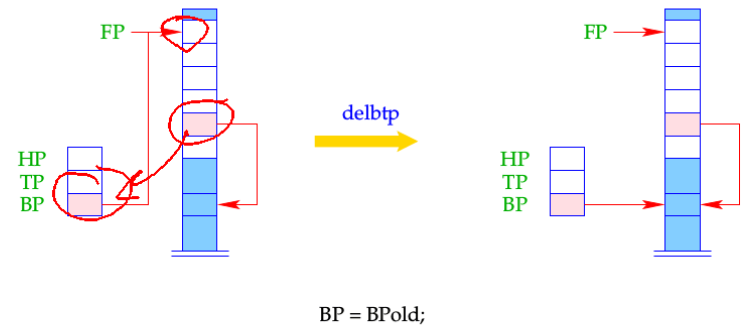
The instruction `setbtp` saves the registers `HP`, `TP`, `BP`:



The instruction `try A` tries the alternative at address `A` and updates the negative continuation address to the current `PC`:



The instruction `delbtp` restores the old backtrack pointer:



33.4 Popping of Stack Frames

Recall the translation scheme for clauses:

```

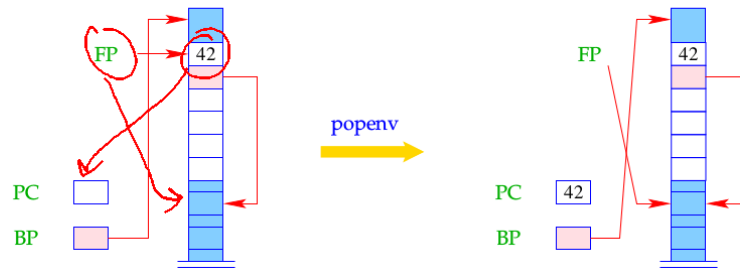
codeC r = pushenv m
           codeG g1 ρ
           ...
           codeG gn ρ
           popenv
    
```

The present stack frame can be **popped** ...

- if the applied clause was the **last** (or **only**); and
- if all goals in the body are definitely **finished**.

⇒ the backtrack point is **older**
 ⇒ $FP > BP$ ↩

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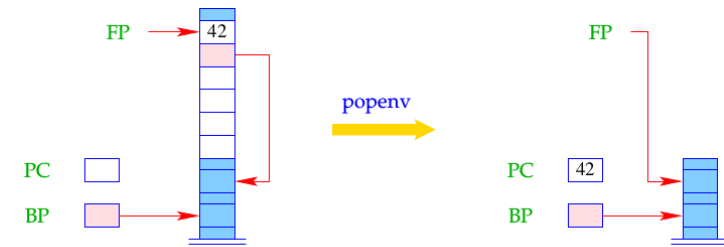


if ($FP > BP$) $SP = FP - 6$;
 $PC = posCont$;
 $FP = FPold$;

If popping the stack frame fails, new data are allocated on top of the stack. When returning to the frame, the locals still can be accessed through the **FP**!

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The instruction **popenv** restores the registers **FP** and **PC** and possibly pops the stack frame:



if ($FP > BP$) $SP = FP - 6$;
 $PC = posCont$;
 $FP = FPold$;

Caveat **popenv** may fail to de-allocate the frame !!!

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34 Queries and Programs

The translation of a program: $p \equiv rr_1 \dots rr_n ? g$
 consists of:

- an instruction **no** for failure;
- code for evaluating the literal g ;
- code for the predicate definitions rr_i .

Preceding query evaluation:

- ⇒ initialization of registers
- ⇒ allocation of space for the globals

Succeeding query evaluation:

- ⇒ returning the values of globals

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```

code p =   init A
           pushenv d
           code_G g ρ
           halt d
           A: no
             code_p rr_1
             ...
             code_p rr_h

```

where $free(g) = \{X_1, \dots, X_d\}$ and ρ is given by $\rho X_i = i$.

The instruction `halt d` ...

- ... terminates program execution;
- ... returns the bindings of the d globals;
- ... causes backtracking — if demanded by the user.

The Final Example

```

t(X) ← X̄ = b      q(X) ← s(X̄)      s(X) ← X̄ = a
p ← q(X), t(X̄)   s(X) ← t(X̄)      ? p

```

The translation yields:

init N	popenv	q/1:	pushenv 1	E: pushenv 1
pushenv 0	p/0: pushenv 1		mark D	mark G
mark A	mark B		putref 1	putref 1
call p/0	putvar 1		call s/1	call t/1
A: halt 0	call q/1	D: popenv	G: popenv	
N: no	B: mark C	s/1: setbtp	F: pushenv 1	
t/1: pushenv 1	putref 1	try E	putref 1	
putref 1	call t/1	delbtp	uatom a	
uatom b	C: popenv	jump F	popenv	

The instruction `init A` is defined by:

```

FP -1
HP 0
TP -1
BP -1

```

init A

```

FP 5
HP 0
TP -1
BP -1

```

0
 -1
 -1
 A

```

BP = FP = SP = 5;
S[0] = A;
S[1] = S[2] = -1;
S[3] = 0;
BP = FP;

```

At address "A" for a failing goal we have placed the instruction `no` for printing `no` to the standard output and halt.

The Final Example

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t(X) ← X̄ = b      q(X) ← s(X̄)      s(X) ← X̄ = a
p ← q(X), t(X̄)   s(X) ← t(X̄)      ? p

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call p/0	putvar 1		call s/1	call t/1
A: halt 0	call q/1	D: popenv	G: popenv	
N: no	B: mark C	s/1: setbtp	F: pushenv 1	
t/1: pushenv 1	putref 1	try E	putref 1	
putref 1	call t/1	delbtp	uatom a	
uatom b	C: popenv	jump F	popenv	

35 Last Call Optimization

Consider the app predicate from the beginning:

```

app(X, Y, Z) ← X = [], Y = Z
app(X, Y, Z) ← X = [H|X'], Z = [H|Z'], app(X', Y, Z')
    
```

We observe:

- The recursive call occurs in the **last** goal of the clause.
- Such a goal is called **last call**.
 - ⇒ we try to evaluate it in the **current** stack frame !!!
 - ⇒ after (successful) completion, we will not return to the current caller !!!

Consider a clause r : $p(X_1, \dots, X_k) \leftarrow g_1, \dots, g_n$
 with m locals where $g_n \equiv q(t_1, \dots, t_h)$. The interplay between $code_C$ and $code_G$:

```

code_C r = pushenv m
           code_G g_1 ρ
           ...
           code_G g_{n-1} ρ
           mark B
           code_A t_1 ρ
           ...
           code_A t_h ρ
           call q/h
    B : popenv
    
```

```

Replacement: mark B      ⇒ lastmark
              call q/h; popenv ⇒ lastcall q/h m
    
```

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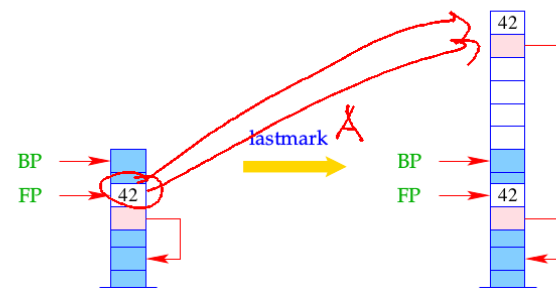
code_C r = pushenv m
           code_G g_1 ρ
           ...
           code_G g_{n-1} ρ
           lastmark
           code_A t_1 ρ
           ...
           code_A t_h ρ
           lastcall q/h m
    
```

```

Replacement: mark B      ⇒ lastmark
              call q/h; popenv ⇒ lastcall q/h m
    
```

If the current clause is not **last** or the g_1, \dots, g_{n-1} have created backtrack points, then $FP \leq BP$.

Then **lastmark** creates a new frame but stores a reference to the **predecessor**:



```

if (FP ≤ BP) {
    SP = SP + 6;
    S[SP] = posCont; S[SP-1] = FPold;
}
    
```

If $FP > BP$ then **lastmark** does nothing.

If $FP \leq BP$, then `lastcall q/h m` behaves like a normal `call q/h`.

Otherwise, the current stack frame is re-used. This means that:

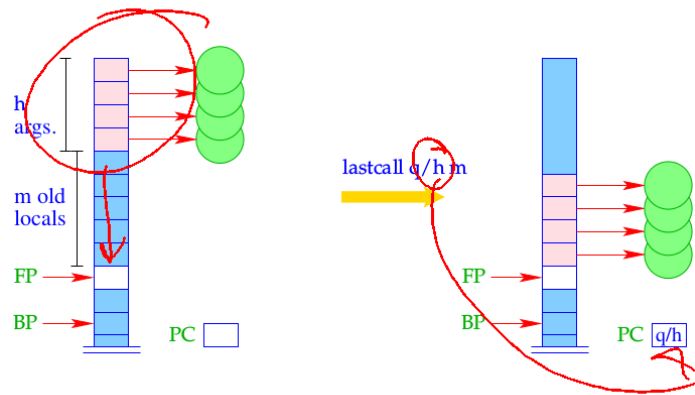
- the cells $S[FP+1], S[FP+2], \dots, S[FP+h]$ receive the new values and
- `q/h` can be jumped to.

```

lastcall q/h m = if (FP ≤ BP) call q/h;
                else {
                  move m h;
                  jump q/h;
                }
    
```

The difference between the old and the new addresses of the parameters `m` just equals the number of the **local variables** of the current clause.

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The difference between the old and the new addresses of the parameters `m` just equals the number of the **local variables** of the current clause.

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Example

Consider the clause:

$a(X, Y) \leftarrow f(\bar{X}, X_1) a(\bar{X}_1, \bar{Y})$

The last-call optimization for `codec r` yields:

```

pushenv 3
mark A
putref 1
putvar 3
call f/2
A: lastmark
   putref 3
   putref 2
   lastcall a/2 3
    
```

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Example

Consider the clause:

$$a(X, Y) \leftarrow f(\bar{X}, X_1), a(\bar{X}_1, \bar{Y})$$

The last-call optimization for `codeC r` yields:

	mark A	A: lastmark
pushenv 3	putref 1	putref 3
	putvar 3	putref 2
	call f/2	lastcall a/2 3

Remark

If the clause is **last** and the last literal is the **only one**, we can skip **lastmark** and can replace **lastcall q/h m** with the sequence **move m n; jump p/n**.

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36 Trimming of Stack Frames

Idea

- Order local variables according to their **life times**;
- Pop the **dead** variables — if possible.

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Example

Consider the **last** clause of the app predicate:

$$\text{app}(X, Y, Z) \leftarrow \bar{X} = [H|X'], \bar{Z} = [\bar{H}|Z'], \text{app}(\bar{X}', \bar{Y}, \bar{Z}')$$

Here, the last call is the **only one**. Consequently, we obtain:

A: pushenv 6		uref 4	bind
putref 1	B: putvar 4	son 2	E: putref 5
ustruct [[]]/2 B	putvar 5	uvar 6	putref 2
son 1	putstruct [[]]/2	up E	putref 6
uvar 4	bind	D: check 4	move 6 3
son 2	C: putref 3	putref 4	jump app/3
uvar 5	ustruct [[]]/2 D	putvar 6	
up C	son 1	putstruct [[]]/2	

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36 Trimming of Stack Frames

Idea

- Order local variables according to their **life times**;
- Pop the **dead** variables — if possible!

Example

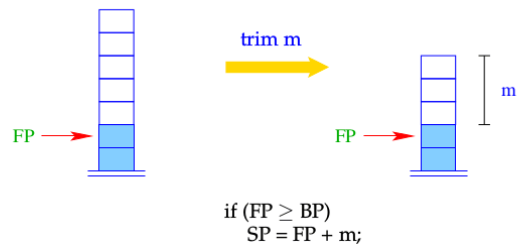
Consider the clause:

$$a(X, Z) \leftarrow p_1(\bar{X}, X_1), p_2(\bar{X}_1, X_2), p_3(\bar{X}_2, X_3), p_4(\bar{X}_3, \bar{Z})$$



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After every non-last goal with dead variables, we insert the instruction `trim` :



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36 Trimming of Stack Frames

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- Order local variables according to their **life times**;
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Example

Consider the clause:

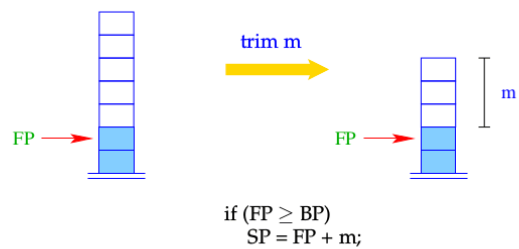
$$a(X, Z) \leftarrow p_1(\bar{X}, X_1), p_2(\bar{X}_1, X_2), p_3(\bar{X}_2, X_3), p_4(\bar{X}_3, \bar{Z})$$

After the literal $p_2(\bar{X}_1, X_2)$, variable X_1 is dead.

After the literal $p_3(\bar{X}_2, X_3)$, variable X_2 is dead.

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After every non-last goal with dead variables, we insert the instruction `trim` :



The dead locals can only be popped if no new backtrack point has been allocated.

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Example (continued)

$$a(X, Z) \leftarrow p_1(\bar{X}, X_1), p_2(\bar{X}_1, X_2), p_3(\bar{X}_2, X_3), p_4(\bar{X}_3, \bar{Z})$$

Ordering of the variables:

$$\rho = \{X \mapsto 1, Z \mapsto 2, X_3 \mapsto 3, X_2 \mapsto 4, X_1 \mapsto 5\}$$

The resulting code:

pushenv 5	A: mark B	mark C	lastmark
mark A	putref 5	putref 4	putref 3
putref 1	putvar 4	putvar 3	putref 2
putvar 5	call p ₂ /2	call p ₃ /2	lastcall p ₄ /2 3
call p ₁ /2	B: trim 4	C: trim 3	

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37 Clause Indexing

Observation

Often, predicates are implemented by case distinction on the first argument.

- ⇒ Inspecting the first argument, many alternatives can be excluded !
- ⇒ Failure is earlier detected !
- ⇒ Backtrack points are earlier removed !!
- ⇒ Stack frames are earlier popped !!!

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Example

Consider again the app-predicate, and assume that the code for the two clauses start at addresses A_1 and A_2 , respectively.

Then we obtain the following four try chains:

```
VAR:  setbtp    // variables  NIL:  jump A1    // atom [ ]
      try A1
      delbtp
      jump A2
CONS:  jump A2    // constructor [[]]
ELSE:  fail      // default
```

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Example The app-predicate:

```
app(X,Y,Z) ← X = [ ], Y = Z
app(X,Y,Z) ← X = [H|X'], Z = [H|Z'], app(X',Y,Z')
```

- If the root constructor is $[]$, only the first clause is applicable.
- If the root constructor is $[]$, only the second clause is applicable.
- Every other root constructor should fail !!
- Only if the first argument equals an unbound variable, both alternatives must be tried :-)

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```

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Then we generate for the predicate p/k:

```
codep rr = p/k: putref 1
              getNode // extracts the root label
              index p/k // jumps to the try block
              tchains rr
A1 : codeC r1
      ...
Am : codeC rm
```

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Then we obtain the following four try chains:

```
VAR: setbtp // variables NIL: jump A1 // atom []
      try A1
      delbtp
      jump A2
CONS: jump A2 // constructor []
ELSE: fail // default
```

The new instruction `fail` takes care of any constructor besides `[]` and `[][]` ...

```
fail = backtrack()
```

It directly triggers `backtracking` ...

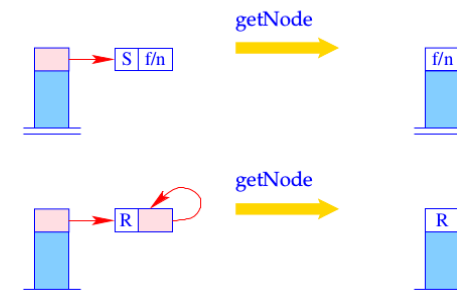
334

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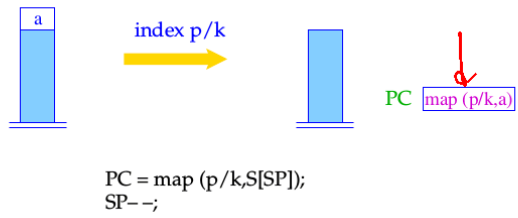
The instruction `getNode` returns "R" if the pointer on top of the stack points to an unbound variable. Otherwise, it returns the content of the heap object:



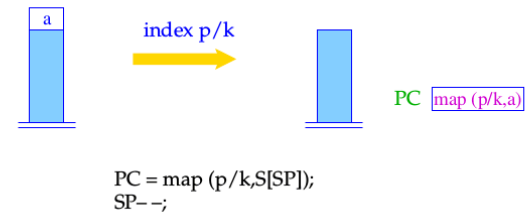
```
switch (H[S[SP]]) {
case (S, f/n): S[SP] = f/n; break;
case (A,a): S[SP] = a; break;
case (R,_): S[SP] = R;
}
```

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The instruction `index p/k` performs an indexed jump to the appropriate try chain:



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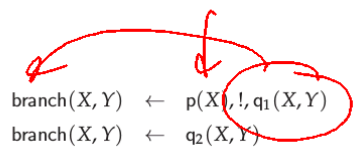
The function `map()` returns, for a given predicate and node content, the start address of the appropriate try chain.

It typically is defined through some hash table ...

38 Extension: The Cut Operator

Realistic Prolog additionally provides an operator "!" (`cut`) which explicitly allows to prune the search space of backtracking.

Example



Once the queries before the cut have succeeded, the choice is committed:
Backtracking will return only to backtrack points preceding the call to the left-hand side ...